# FURUNO INSTALLATION MANUAL

## **COLOR MULTI-SECTOR SONAR**

MODEL CH-34/36



## ©FURUNO ELECTRIC CO., LTD.

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-Your Local Agent/Dealer

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(ATAT)

# **SAFETY INSTRUCTIONS**

"DANGER", "WARNING" and "CAUTION" notices appear throughout this manual. It is the responsibility of the installer of the equipment to read, understand and follow these notices. If you have any questions regarding these safety instructions, please contact a FURUNO agent or dealer.



This notice indicates a potentially hazardous situation which, if not avoided, will result in death or serious injury.



This notice indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.



This notice indicates a potentially hazardous situation which, if not avoided, could result in minor or moderate injury, or property damage.

# **WARNING**



Only qualified personnel should work inside the equipment.

This equipment uses high voltage electricity which can shock, burn, or cause death.

Turn off the power at the ship's mains switchboard before beginning the installation. Post a warning sign near the switchboard to ensure that the power will not be applied while the equipment is being installed.

Serious injury or death can result if the power is not turned off, or is applied while the equipment is being installed.

# **A** CAUTION



Ground the equipment.

Ungrounded equipment can give off or receive electromagnetic interference or cause electrical shock.

Confirm that the power supply voltage is compatible with the voltage rating of the equipment.

Connection to the wrong power supply can cause fire or equipment damage. The voltage rating appears on the label at the rear of the equipment.

# **A** CAUTION

Keep oil away from eyes. Wear protective goggles when working with the oil. The oil cause inflammation of the eyes.

Do not touch the oil. The oil can cause inflammation of the skin. Wear protective gloves when working with the oil. Do not ingest the oil. Diarrhea or vomiting

can result.

Keep the oil out of reach of children.

EMERGENCY
If the oil enters the eyes, flush with clean
water about 15 minutes. Consult a physici-

If oil contacts skin, wash with soap and water.

If the oil is ingested, see a physician immediately.

#### DISPOSAL OF OIL AND ITS CONTAINER

Dispose of oil and its container in accordance with local regulations. For further informaton, contact place of purchase.

#### **STORAGE**

Seal container to keep out foreign material. Store in dark place

Manual Raise/Lower of Transducer
Supply ship's mains to the hull unit
and turn of the breaker on the hull unit.
Then while pressing the brake-off
switch, turn hand crank to raise or lower
the transducer.

Observe maximum allowable ship's speed of 18 knots during operation and 15 knots while raising/lowering transducer.

The zinc block attached near the transducer must be replaced yearly.

The junction between the transducer and main shaft may corrode, which can result in loss of the tansducer or water leakage inside the ship.

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## SPECIFICATIONS OF COLOR MULTI SECTOR SONAR CH-34/36

1. Display System

PPI display on high resolution 12" (CH-34) or 14" (CH-36)

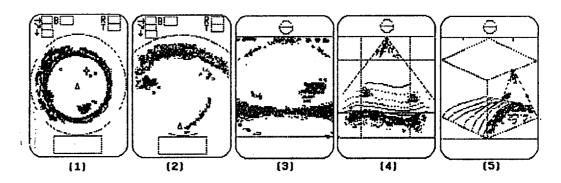
color CRT

2. Picture Color

16 or 8 colors depending on signal strength

3. Display Mode

- (1) Normal sonar mode display\*
- (2) Expanded sonar mode display
- (3) Vertical fan mode display \*
- (4) 3D mode display (front view)\*\*
- (5) 3D mode display (slant view)\*\*



- \* : E/S combination display is optionally available in modes (1) and (3).
- \*\*: Optionally available.

#### 4. Range/Train Speed

(1) Sonar Mode

	) Jonar .	·····	tion Range		Train
	Meter	Feet	Fathom	Remark	Speed* (sec./360°)
1	0-50	0-200	0-40		3.8
2	0-100	0-300	0-60		4.3
3	0-150	0-400	0-80		4.8
4	0-200	0-600 0-500	0-100	60kHz 162kHz	5.4
5	0-250	0-800 0-600	0-120	60kHz 162kHz	6.4
6	0-300	0-1000 0-800	0-160 0-140	60kHz 162kHz	6.7
7	0-400 0-350	0-1500 0-1000	0-250 0-160	60kHz 62kHz	7.0
8	0-500 0-400	0-2000 0-1200	0-300 0-200	60kHz 162kHz	7.6
9	0-600 0-450	0-2500 0-1500	0-400 0-250	60kHz 162kHz	8.6

10	0-800 0-500	0-3000 0-2000	0-500 0-300	60kHz 162kHz	10.0
11	0-1200 0-600	0-4000 0-2500	0-700 0-400	60kHz 162kHz	12.0
12	0-1600 0-800	0-5000 0-3000	0-900 0-500	60kHz 162kHz	14.0

<sup>\*:</sup> Measured at " Fast Train" mode.

Display sector width is selected among 45°, 90°, 135°, 180°, 225° and 360°.

(2) Vertical Fan Mode

(2) Vertical Fall Mode							
	Vertic	Vertical Detection Range**					
	Meter	Feet	Fathom	(sec./180°)			
1	0-20	0-100	0-20	4.8			
2	0-40	0-150	0-30	4.8			
3	0-60	0-200	0-40	4.8			
4	0-80	0-250	0-50	4.8			
5	0-100	0-300	0-60	4.8			
6	0-120	0-400	0-70	5.6			
7	0-160	0-500	0-80	7.5			
8	0-200	0-600	0-100	9.4			
9	0-240	0-800	0-120	11			
10	0-280	0-1000	0-160	13			
11	0-320	0-1200	0-200	15			
12	0-400	0-1500	0-250	19			

<sup>\*:</sup> Selected "Fast Scan" on the sub-panel 2.

Display sector width is selected among 36°, 60°, 96°, 120°, 156° and 180°.

(3) Echo Sounder Range

		Display Range							
Range	Meter	Feet	Fathom	Uni	Shift Ra	Max. Shift Range			
1	0-40	0-100	0-20	20M	50F	10FA			
2	0-80	0-200	0-40	20M	50F	10FA	1000M		
3	0-160	0-400	0-80	50M	100FT	20FA	3000FT 500FA		
4	0-240	0-600	0-120	100M	200FT	50FA	]		
5	0-320	0-1000	0-160	100M	200FT	50FA			

#### 5. Off Center

Four-position selected by TRAIN knob in expanded sonar mode.

Two-position selected by TILT knob in vertical fan mode.

6. Numeric Information and Display Scale/Mark

Training Data

Range, Tilt angle

Trackball Data Slant, Horizontal range, depth, Bearing

<sup>\*\*:</sup> Horizontal range is either equal to or 50% of the vertical range.

R/B Mark Data Range, Bearing

Scale/Marker Bearing scale, Sector center mark, Own

ship's mark, Trackball and Event

markers

Latitude/longitude, courseline and north mark are displayed when nav sensor is connected.

7. Audio Monitor

Output 4W,  $4\Omega$  using external speaker CA-150 (op-

tion)

Frequency 900/1000Hz selected by internal settings

8. Transceiver

Frequency: 60 or 162kHz

#### **Output Power and Beamwidth**

#### (1) Sonar Mode

		Beamwidth at -3dB					
	Output* Power		TX		RX		
Freq		Н	or.	Vert.	Hor.	Vert.	
60kHz	1.0kW	60° (FAST	16°**	13°	16°	13°	
162kHz	1.5kW	TRAIN "ON")	9°**	6°	8°	6°	

\*: Output power can be reduced in three steps.

\*\*: Fast Train mode "OFF"

#### (2) Vertical Fan Mode

		Beamwidth at -3dB				
	Output* Power	TX		R	X	
Freq.	1 OWC	Hor.**	Vert.	Hor.*	Vert.	
60kHz	1.0kW	16°	13°	16°	13°	
162kHz	1.5kW	9°	6°	8°	6°	

\*: Output power can be reduced in three steps.

\*\*: 30° approx. when selecting "WIDE" beamwidth on the menu.

Pulselength: 0.2 to 10.6ms, fixed or varied according to

the range in use (selectable on the Menu)

3

#### 9. Training

Mode	Sonar (horizontal) mode	Vertical Fan mode
Train Step	45° or 6° step	Auto Train: 15° step Manual: 6° step
Auto Train Sector	-	90°, 180° or 360°
Manual Train Sector	lanual Train Sector – H	

#### 10. Tilting

Mode	Sonar (horizontal) mode	Vertical Fan mode		
Tilt Range	+5° to 90°	0° to +180°		
Tilt Step	1°/step	6° or 3°/step		
Stabilizer (option)	Motion sensor MS-100 stabilizes sounding beam against rolling and pitching of up to ±20°.			

11. Transducer Raise/Lower

Transducer travel: 400mm

Raise time: approximately 10 sec (24/32Vdc) Lower time: approximately 8 sec (24/32Vdc)

12. Allowable Ship's Speed 18 knots (15 knots during raise/lower operation)

13. Power Supply and Consumption

24/32VDC, 200W (300W during transducer raise/lower) 100/110/200/220VAC, 50/60Hz with two sets of rectifiers

RU-1746B-2

14. Ambient Condition

Temperature: 0°C to 50°C Humidity: less than 95%

#### **COMPLETE SET**

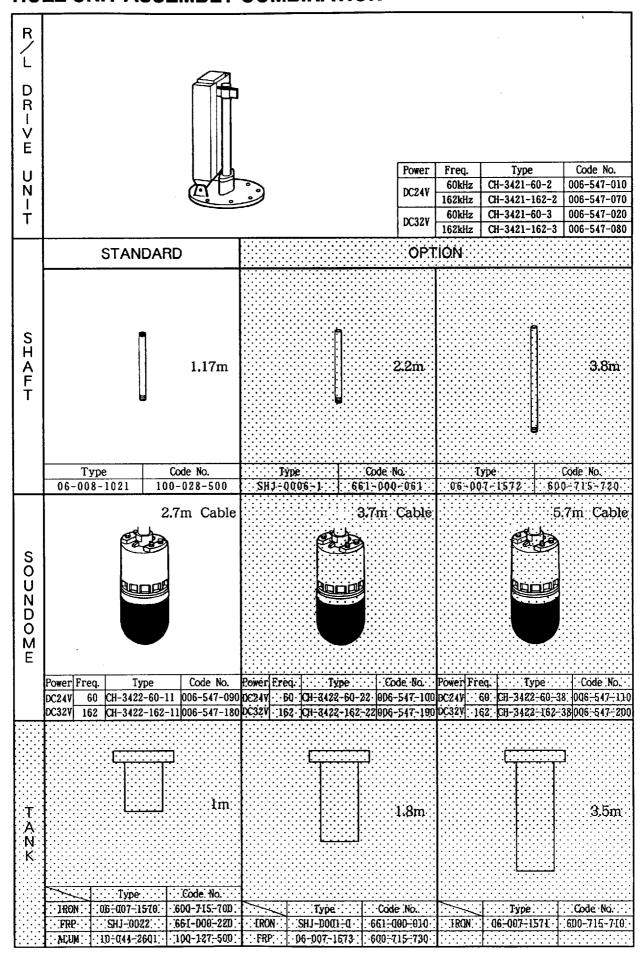
#### **STANDARD SUPPLY**

No.	Name	Туре	Code No.	Qty	Weight (kg)	Remarks
1	Display Unit	CH-340-E CH-360-E	000-068-410 000-068-412	1	16 20	12" CRT 14" CRT
2	Transceiver Unit	CH-341-60 CH-341-162	000-068-414 000-068-417	1	8.5	60kHz 162kHz
3	Hull Unit	CH-342		1	55	Specify the power supply voltage, frequency and main shaft length when ordering.
4	Accessories	FP02-03200	000-014-745	1		
5	Installation Materials	CP06-00800 CP06-00810 CP06-00820	000-068-443 000-068-444 000-068-445	1		With 15m cable (STD) With 30m cable With 50m cable
6	Spare Parts	SP06-00800	000-068-442	1		

#### **OPTION**

No.	Name	Туре	Code No.	Weight (kg)	Remarks
1	Motion Sensor	MS-100	000-069-256	2	
2	Remote Control	CH-343-E	000-068-449	0.4	
3	Rectifier	RU-1746B-2	000-030-439 000-030-440	17	For 110VAC For 220VAC
4	Retraction Tank	06-007-1570(steel) SHJ-0001(steel) 06-007-1571(steel) SHJ-0022(FRP) 06-007-1573(FRP)	600-715-700 661-000-010 600-715-710 661-000-220 600-715-730		For 1.1m shaft For 2.2m shaft For 3.5m shaft For 1.1m shaft For 2.2m shaft
5	Interface	CH-344	000-068-447		For connection of external equipment.
6	E/S Interface	VI-1100A	000-021-803	2	
7	External Speaker	CA-150	000-109-070		
8	Handle	OP03-70	008-423-420		For CH-36 only

#### **HULL UNIT ASSEMBLY COMBINATION**



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		<u></u>	TYPE FP02-03		
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1	HOOD ASSY.	290	CODE NO 008-223		
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	12インチフィルター		02-083-1601-2	1	
2	12" FILTER	202			
		340	CODE NO 100-103		
	ヒ"ニールカハ"ー		02-102-1301-1	l	
3	PLASTIC COVER	10 rununo 330		1	
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2	FILTER ASSY.	258			1		
		7	CODE NO 002-00	7-290			
	ヒ"ニールカハ"ー	380	10-044-0031-	1			
3	PLASTIC COVER	435			1		
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3	COPPER STRAP			50				1	FOR DISPLAY
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	事材料表	CH-344	外 部インターフェース		
	STALLATION MATERIALS		INTERFACE MODULE		
番号	名 称	略図	型名/規格	数量	用途/備考
Na	N A M E	OUTLINE	DESCRIPTIONS	Q'TY	REMARKS
	コネクタ	47 A (VED)	SRCN6A13-3P	:	
1	CONNECTOR	ø21 <b>1</b>		_ 1	
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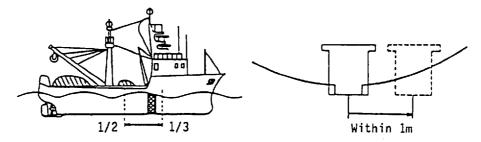
### **CHAPTER 1. MOUNTING**

#### 1.1 Hull Unit

#### 1.1.1 Installation Position of Hull Unit

Discussion and agreement are required with the dockyard and the ship owner in deciding the installation position of the hull unit. When deciding the installation position, the following points should be taken into account.

1) Select an area where propeller noise, cruising noise, bubbles and interference from turbulence are at a minimum. Generally the position at 1/3 to 1/2 of the ship's length from the bow on or near the keel is optimum. On-the-keel installation is advantageous for minimizing oil consumption in comparison with the off-the-keel. In case the hull unit can not be installed on the keel, the center of the retraction tank should be within 1m of the keel so as to minimize the rolling effect.



Installation Position of Hull Unit

- 2) Select a place where interference from other equipment is minimal. It should be at least 2.5m away from the transducers of other equipment.
- 3) An obstacle in the fore direction not only causes shadow zone but also aerated water, resulting in poor sonar performance.

#### 1.1.2 Mounting Retraction Tank

NOTE: When retraction tank is produced in the field, the inner diameter should be  $\varphi$ 190 $\pm$ 0.5mm. If it is bigger, the shaft may be damaged by vibration.

#### Mounting Method

A typical mounting method is shown on page 1-3. Consult the ship's owner, dockyard and user to determine the mounting method. Pay attention to safety (strength, watertightness, etc.) for the first thing and then to the ease of maintenance and inspection.

#### **Deciding Tank Length**

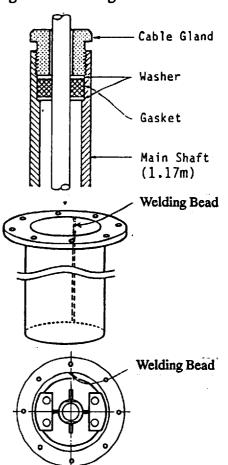
Cut off excess portion of the tank so that the transducer is lowered into water as deep as possible.

In addition, take note of the tank length Lt. It is necessary to determine the length of the main shaft as described in the next paragraph "Assembling and Mounting of Hull Unit".

Main Shaft Length = Lt + 110 (mm)

Note

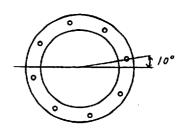
- 1. Do not cut off the 1m retraction tank. If some portion is cut off, you may also have to cut off the top part of the main shaft, destroying the watertight construction of the 1.17m shaft.
- 2. When the retraction tank is made locally, finish it so that the welding bead may not protrude on the inner surface of tank. The tank guide will hit the bead, causing the motor burn-out. Also when installing the tank, do not position the welding bead in the ship's fore-aft-line.
- 3. When you want to use other maker's tank, check the dimensions strictly. Use the same dinession's tank by referring to page 1-19.

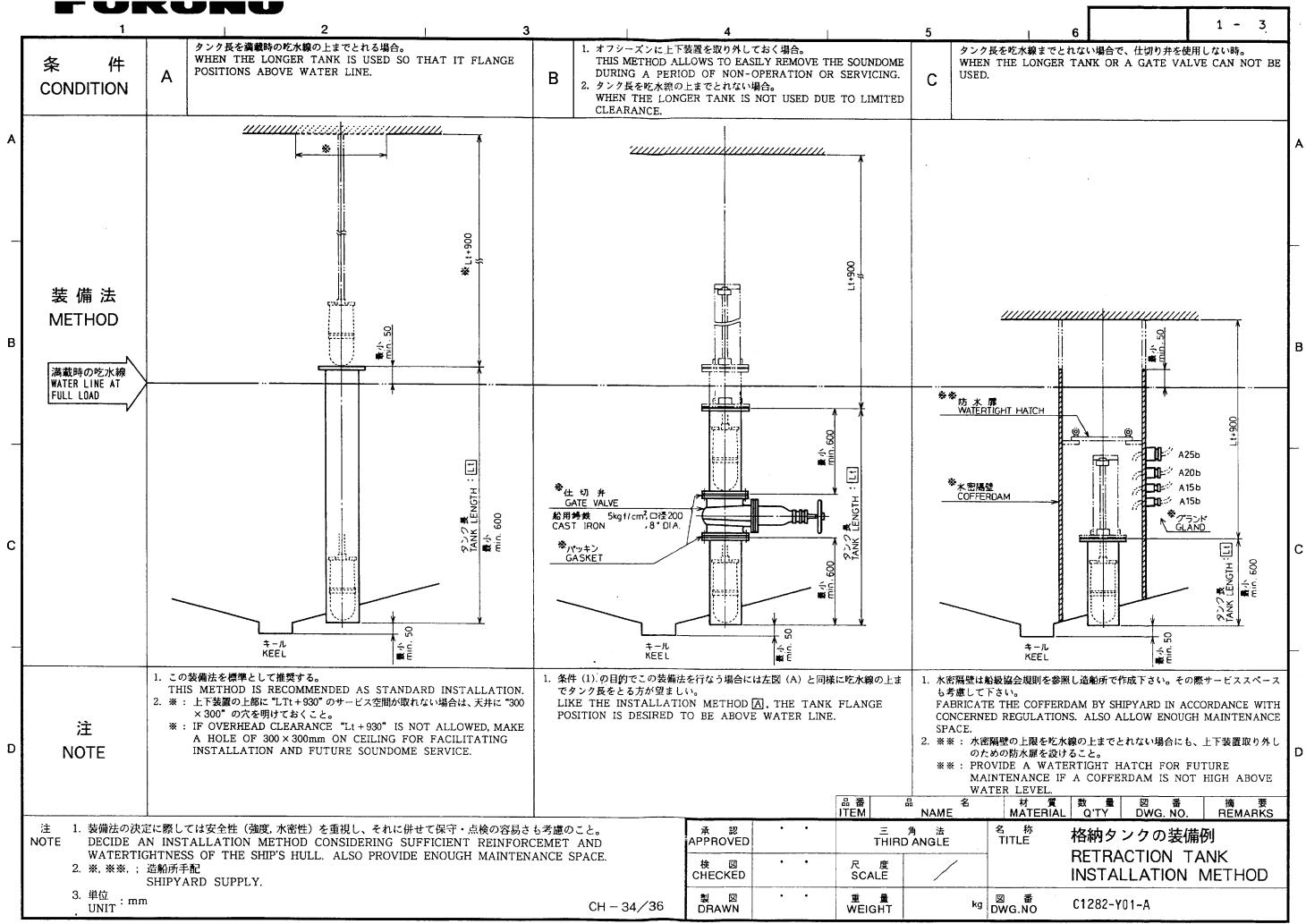


#### Mounting

Install the tank referring to the drawings on page 1-19 to 1-26.

Note: Locate one of the bolt holes by 10° to port to minimize mechanical shock applied to the raise/lower block due to ship's rolling and pitching.



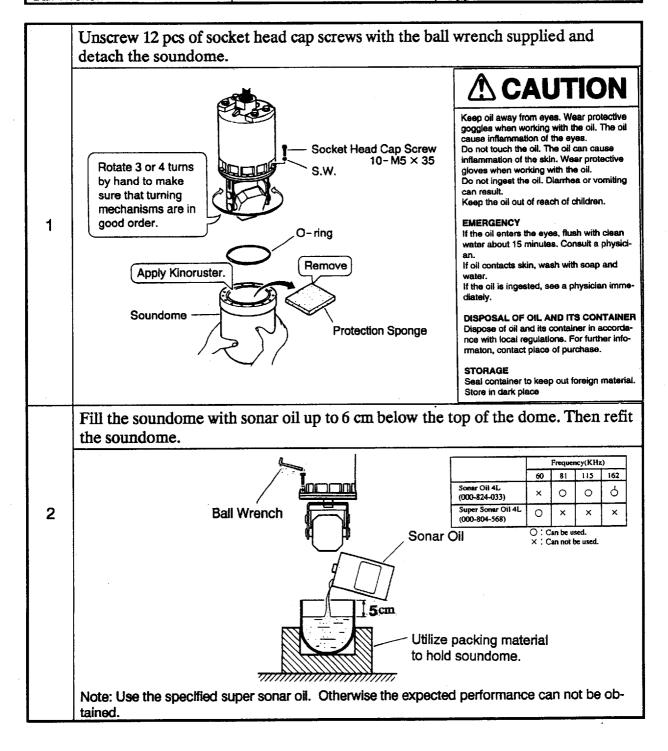


#### 1.1.3 Assembling and Installation of Hull Unit

You will receive the hull unit disassembled to parts shown on page 1-10. To assemble them, follow the procedure shown below.

**Necessary Tools** 

Name	Specification	Remarks
Spanner	For M10 (Hex. size 17mm)	
Spanner	For M20 (Hex. size 20mm)	
Pipe Wrench	55mm	
Ball Wrench		supplied as a hull unit kit



Cut the main shaft to the length of Lt + 110, where Lt is the length of the retraction tank.

Supplied Length:1.17m(2.2m, 3.8m)

Supplied Length:1.17m(2.2m, 3.8m)

Lt + 110

Chamfer the edge to protect O-ring from damage.

Note: When the tank length is 1m, do not cut the 1.17m main shaft.

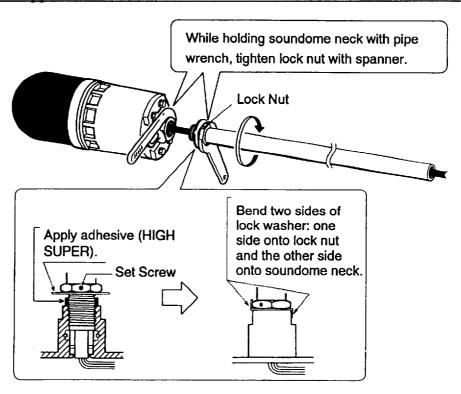
Fix the main shaft to the soundome assembly as follows.

1. Screw lock nut onto main shaft

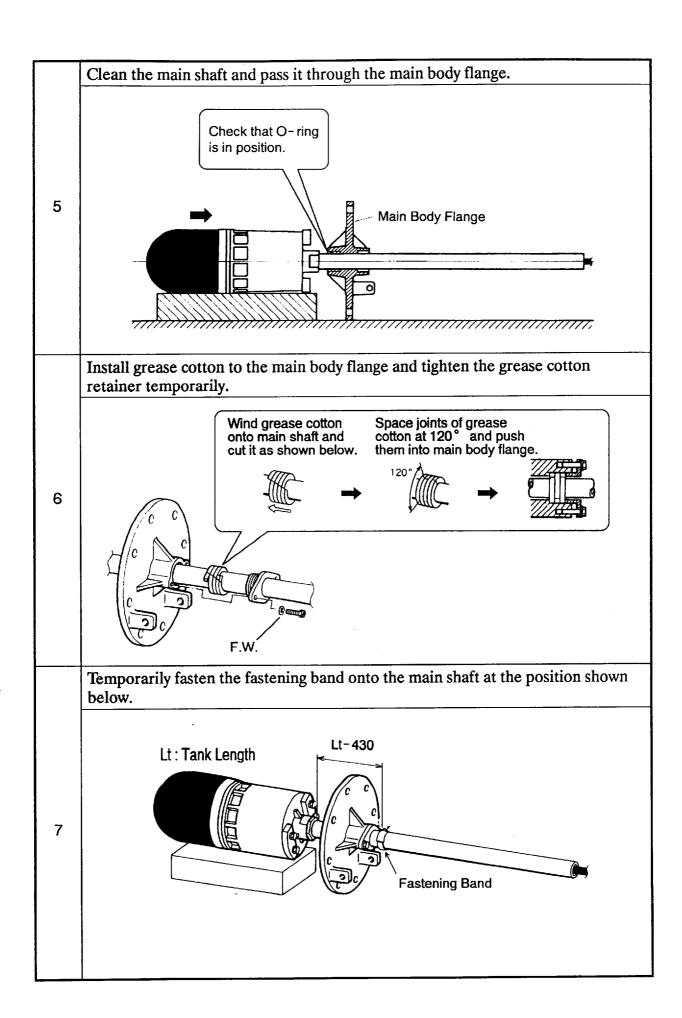
3

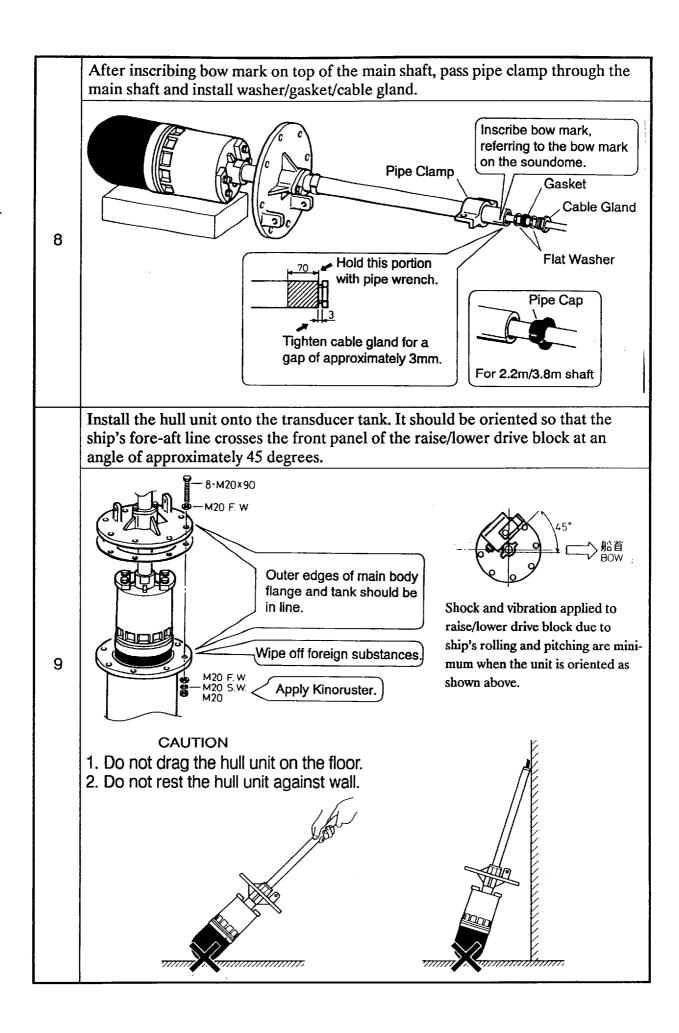
4

- 2. After fully screwing main shaft into soundome neck, unscrew it by four turns and apply adhesive (HIGH SUPER) to the threads.
- 3. Screw in main shaft completely and tighten lock nut with spanner.
- 4. Tighten socket-set screw on lock nut.
- 5. Bend two sides of lock washer by using hammer; one side upward onto lock nut and the opposite side downward onto soundome neck.



Note: Do not hammer lock washer in such a direction that the lock nut is unscrewed.



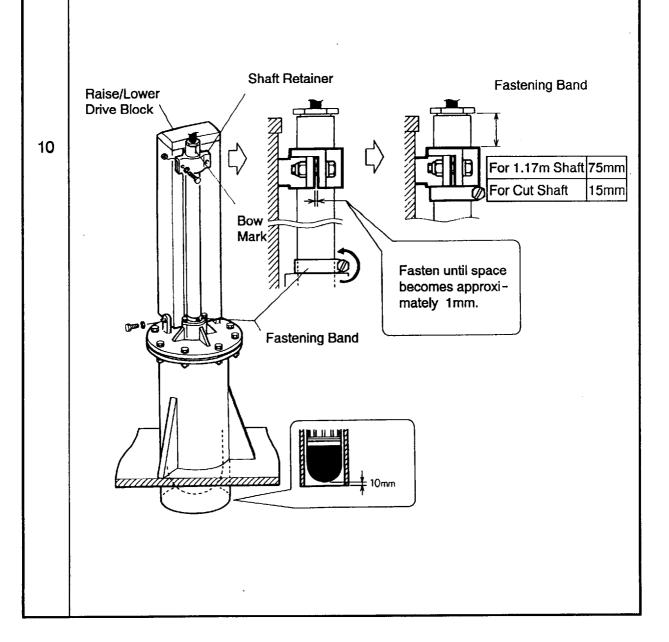


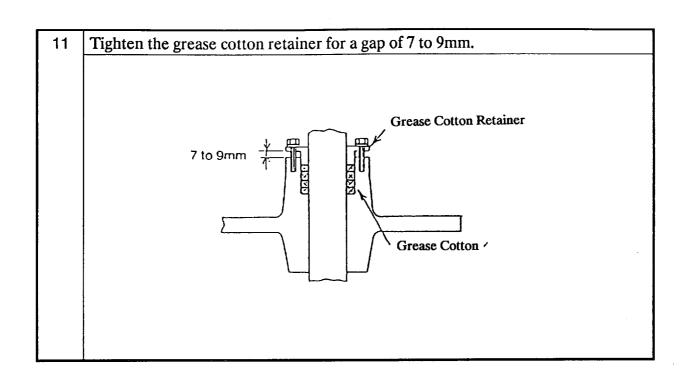
Install the raise/lower drive block in the following order.

- 1. Rotate the main shaft so that bow mark faces ship's bow.
- 2. Install the raise/lower drive block onto the main body flange.
- 3. Fix the main shaft with the shaft retainer.
- 4. Loosen the fastening band and slide it up to the shaft retainer and fasten it.
- 5. Check that the distance from the top of the main shaft to the top of the shaft retainer is as follows.

1.17m main shaft ----- 75mm Main shaft cut at Lt + 110 ----- 15mm

If not as shown above, loosen shaft retainer and fastening band to adjust the distance. This will place the bottom of soundome 10mm above the bottom of the retraction tank when the soundome is retracted.





## **HULL UNIT KIT**

番号 No.	名 称 NAME	略 図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	上下動部 RAISE/LOWER DRIVE ASSEMBLY		CODE NO.		
2	旋回部 SOUNDOME ASSEMBLY		CODE NO.		
3	フランジ MAIN BODY FLANGE		06 - 018 - 3202 CODE NO. 100 - 162 - 031	1	
4	グリスコットン GREASE COTTON	500	□9.5 * 0.6M *  CODE NO.   000 - 859 - 013	(1)	
5	グリスコットン押え台 GREASE COTTON RETAINER	18	SHJ - 0003 - 1 CODE NO. 661 - 000 - 031	(1)	
6	トラニオンポルト TRUNNION BOLT	35 \$\phi 12	06 - 013 - 3203 - 2 CODE NO. 100 - 143 - 912	(2)	
7	フランジパッキン GASKET	ø350	SHJ - 0009 - 1 CODE NO. 661 - 000 - 091	(1)	
8	Oリング O RING	648 0,3	JISB2401 - 1A - P42  CODE NO. 000 - 851 - 142	(1)	
9	スリ割付六角ボルト SLOTTED HEX. BOLT	25	M8 × 25 SUS304 CODE NO. 000 - 801 - 701	(2)	
10	バネ座金 SPRING WASHER	28	M16 CODE NO. 000 - 864 - 265	(2)	
	-				
12	上下シャフト MAIN SHAFT	1170 •42[()] 2200 •42[()] ))	06 - 008 - 1021 - 0  CODE NO.   100 - 028 - 500  SHJ - 0006 - 1	1	
		3800 \$42[()	CODE NO. 661 - 000 - 061  06 - 007 - 1572  CODE NO. 600 - 715 - 720		
13	ジェビリークリップ FASTENING BAND	Maniniman	1X SUS304  CODE NO. 000 - 801 - 857	1	
14	止めナット LOCK NUT	57 112	06 - 013 - 2401 - 0 CODE NO.   100 - 098 - 730	1	
15	六角穴付止めネジ SOCKET SET SCREW	¢4 (100)	M4 × 5 SUS CODE NO. 000 - 801 - 527	1	

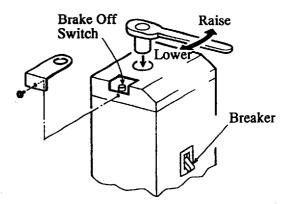
希号 No.	名 称 NAME	略 図 OUTLINE	型名/規格 DESCRIPTIONS	数置 Q'TY	用途/備考 REMARKS
16	回り止め <b>変金</b> STOPPER WASHER	•70	06 - 013 - 2402 - 0	I	
		<del></del>	CODE NO. 100 - 098 - 740		
17	パイプキャップ PIPE CAP	35	08 - 007 - 1307 - 0	1	
			CODE NO. 600 - 713 - 070		
18	椿め付けグランド CABLE GLAND		06 - 008 - 1031 - 0 CODE NO.   100 - 028 - 520	1	
19	<b>遊金</b> WASHER	37.4	06 - 018 3302 - 0	2	
20	ガスケット	37	CODE NO. 100 - 162 - 051 06 - 018 - 3303 - 1	1	
	GASKET		CODE NO. 100 - 162 - 061		
21	六角ポルト HEX. BOLT	40	M10 × 40	2	·
	IIIA. IVIJI		CODE NO. 000 - 862 - 184		
22	パネ座金 SPRING WASHER	\$18 (S)	M10 SUS304	2	
			CODE NO. 000 - 864 - 261		7.00
23	Uナット U – NUT	7	M10 SUS304	2	
		1 80 -1	CODE NO. 000 - 863 - 930		
24	六角ポルト HEX. BOLT	•20		8	
		4	CODE NO. 000 - 801 - 893		
25	ミガキ平座金 FLAT WASHER	440	M20 SUS304  CODE NO. 000 - 864 - 136	16	
		424	CODE NO.   COO - 804 - 130		
26	パネ座金 SPRING WASHER	634	M20 SUS304 CODE NO. 000 - 864 - 270	8	
-		35			
27	六角ナット NEX. NUT	16	M20 SUS304 CODE NO. 000 - 863 - 116	16	
	<b>△四十七→四七四・</b> 1.→4	- 054			
28	金属すきま腐触防止剤 ANTI - CREVICE CORROSION SEALANT	INCORASTER 15	KINORUSTER 855  CODE NO. 000 - 801 - 025	1	
		80	ハイスーパー		
29	セメダイン ADHESIVE	32 15 セメタイン	HIGH SUPER  CODE NO. 000 - 856 - 520	1	
	V2 27	103/-/(35)7			60KHz
30	ソナーオイル SONAR OIL	238	CODE NO. 000 - 824 - 033	1	Super Sonar Oil 4L (000-804-568)
31	ポールレンチ BALL WRENCH	135	HEX. SIZE 4mm	1	
		A-	CODE NO. 000 - 804 - 123		
			222 10		
	···-		CODE NO.		

1 - 10

#### 1.1.4 Manual Raise/Lower of Transducer with Hand Crank

This check should be performed after all cable wirings are completed: ship's mains should be supplied to the hull unit. Otherwise the magnetic brake of the raise/lower motor operates, disabling the manual raise/lower.

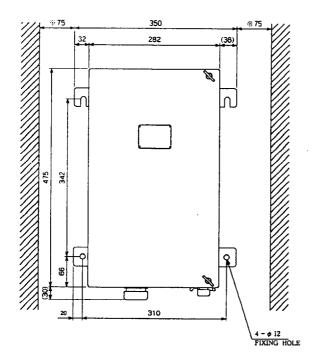
- 1. Turn off the breaker on the hull unit.
- 2. Remove the brake-off switch cover.
- 3. Set 19mm socket wrench and turn it while pressing the brake-off switch.
- 4. Check that the transducer can be raised/lowered smoothly with a constant force from the upper to the lower limit positions. If not, centers of the main body flange and the retraction tank are not aligned. Adjust the hull unit mounting position.

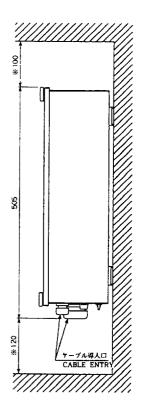


Raising/lowering manually without connecting ship's mains may cause motor damage.

#### 1.2 Transceiver Unit

- 1) Since the transceiver unit generates heat, install it on a dry well ventilated location.
- 2) Floor or bulkhead mounting is allowed.
- 3) Allow service and maintenance space.

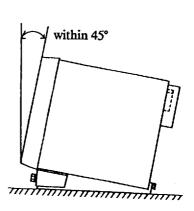




#### 1.3 Display Unit

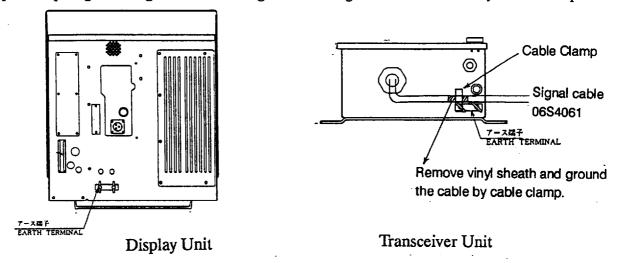
To install the display unit, the following conditions should be considered.

- 1) Place where operating personnel are able to control the unit easily while observing the fishing ground or area surrounding the vessel.
- 2) Place at least 1m away from magnetic components (radar magnetron, loudspeaker, high power transformer, etc.) and magnetic compass.
- 3) Place where the unit is not exposed to direct sunlight, water splash or hot air.
- 4) Place where the CRT face is within 45 from the vertical.



#### 1.4 Unit Grounding

Since all units are very sensitive to noise, they should be grounded to ship's hull with specified copper strap or grounding wire. And also ground the signal cable 06S4061 by cable clamp.



#### 1.5 Motion Sensor MS-100 (Option)

The MS-100 measures ship's rolling and pitching angles with sensors using the principles of the gyroscope. Following in the footsteps of its predecessor model BS-704, the MS-100 is free from error caused by ship's vertical and horizontal motion and can be installed at any convenient location. However ship's semipermanent inclination due to loading imbalance, etc. can not be detected and should be compensated at installation as described in chapter 3.

#### 1.5.1 Installation Site

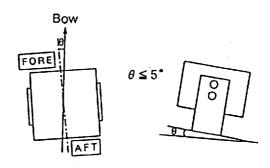
Basically, the unit can be installed at any location, provided that the following places are avoided. Especially pay attention to vibration which may be the main cause of erroneous reading. The recommended place is on the floor in the bridge.

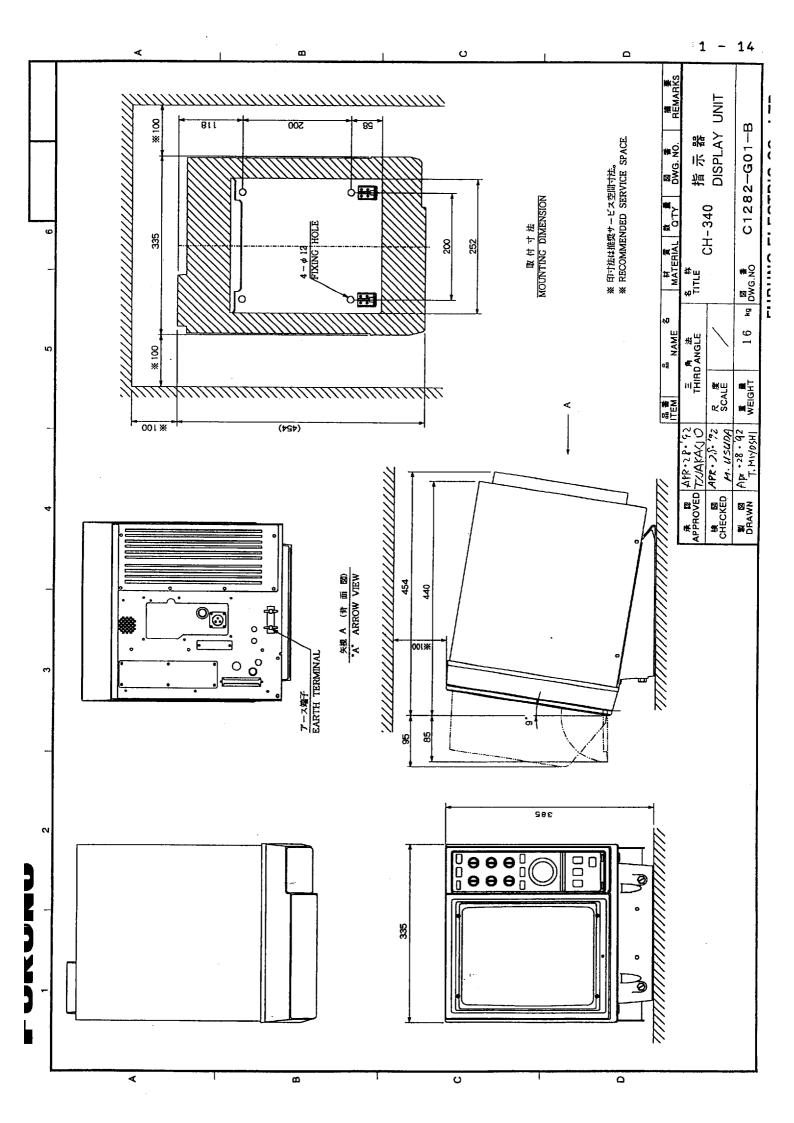
- 1) Place subjected to intense vibration; engine room, thin bulkhead, ceiling, etc.
- 2) Place exposed to air and splash.
- 3) Place with high temperature. (50°C or more)

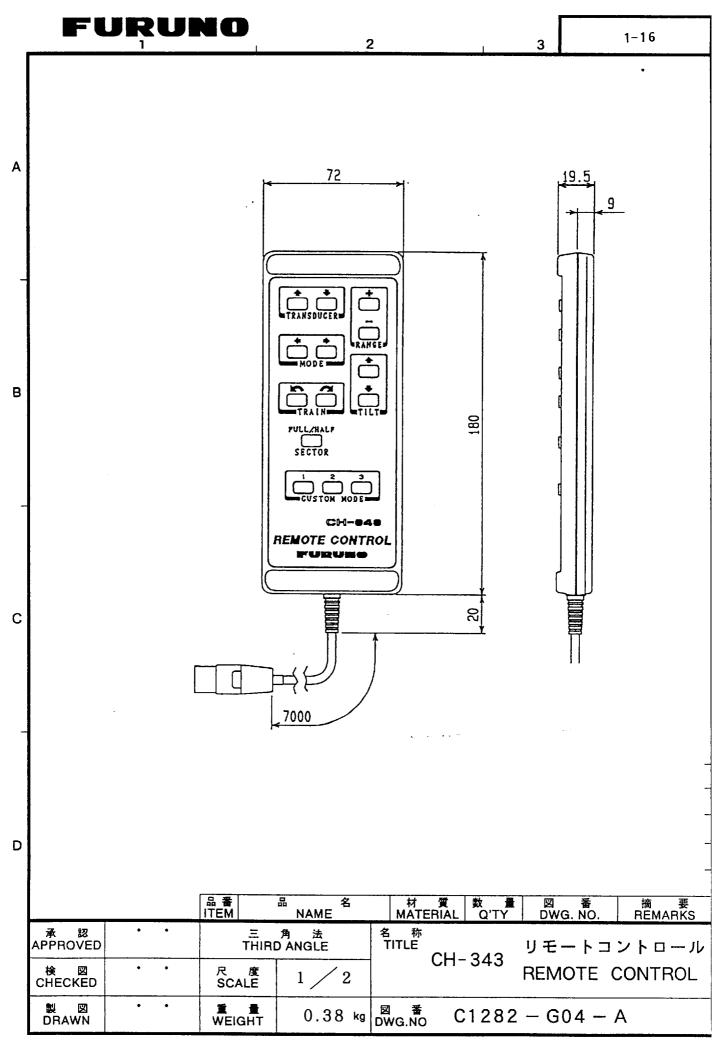
Further, do not mount it on the hull unit where intense vibration is expected.

#### 1.5.2 Installation

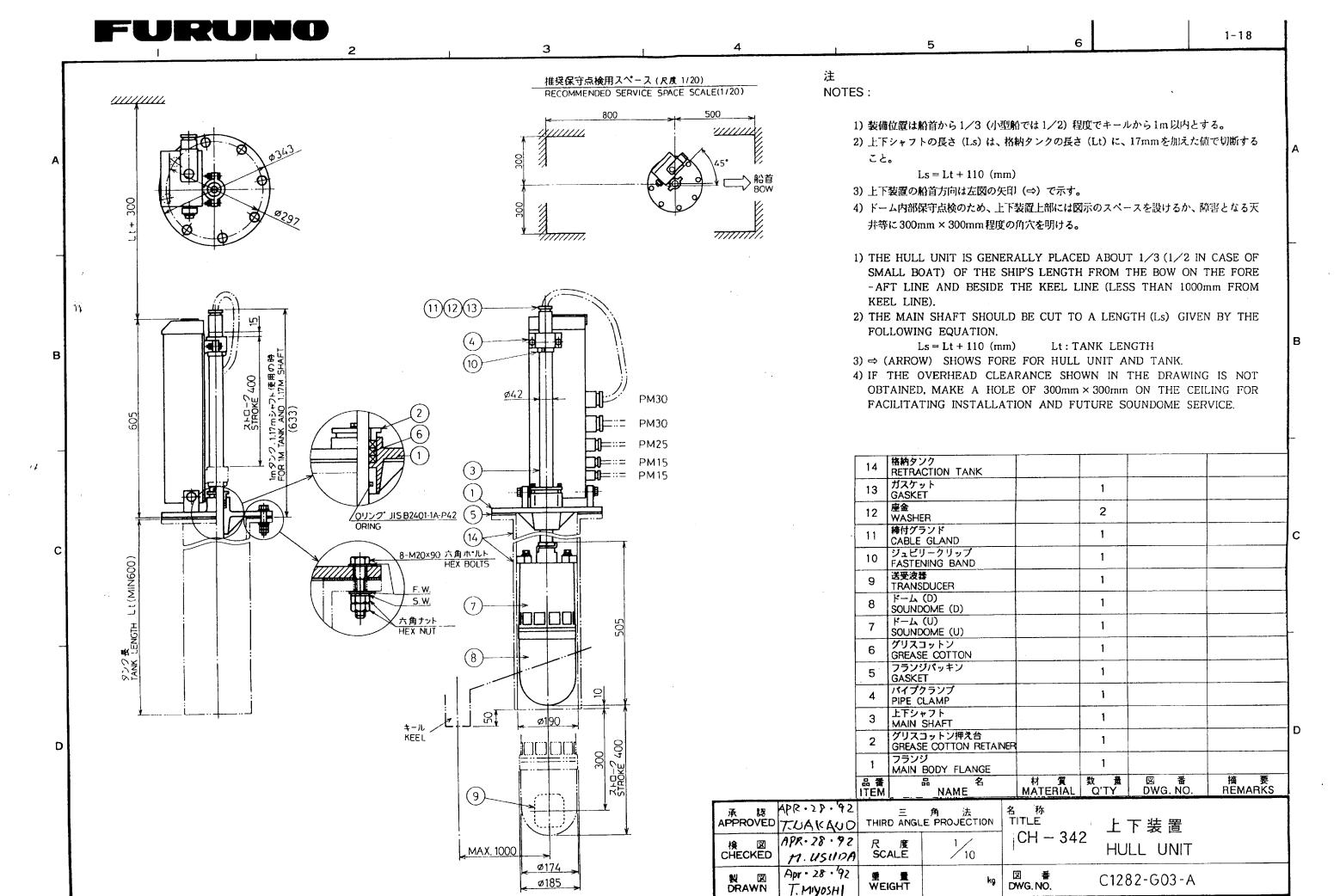
Orient the FORE mark on the unit toward the ship's bow and mount the unit level to within 5° in all directions

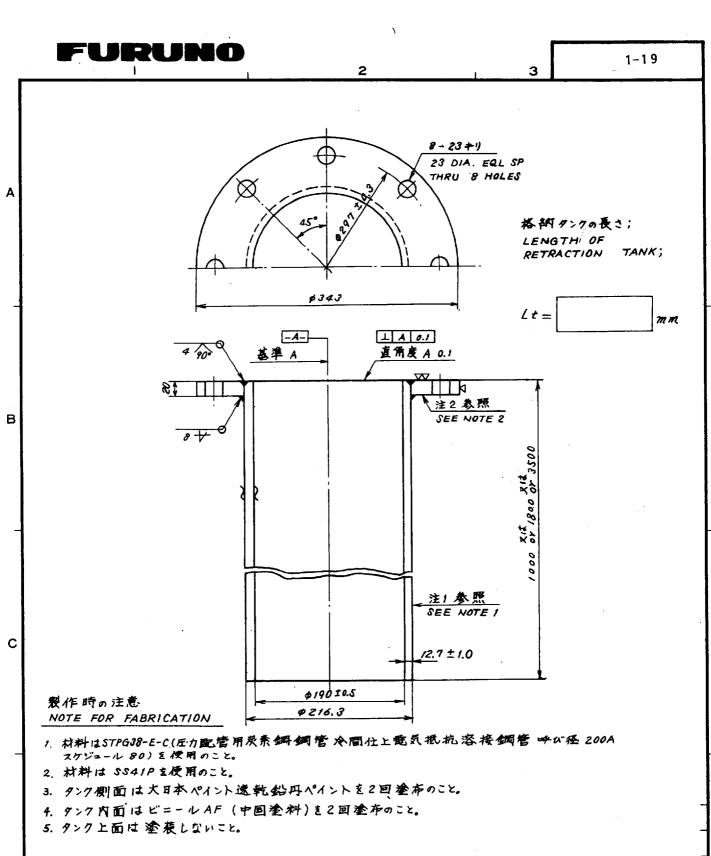






FURUNO ELECTRIC CO., LTD.

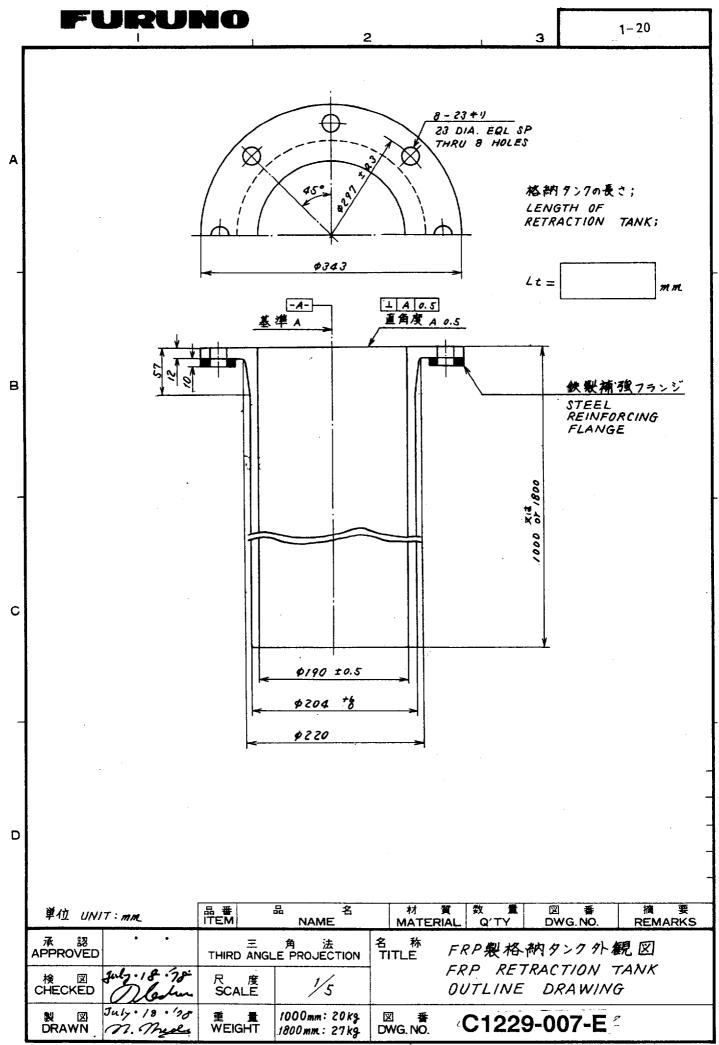


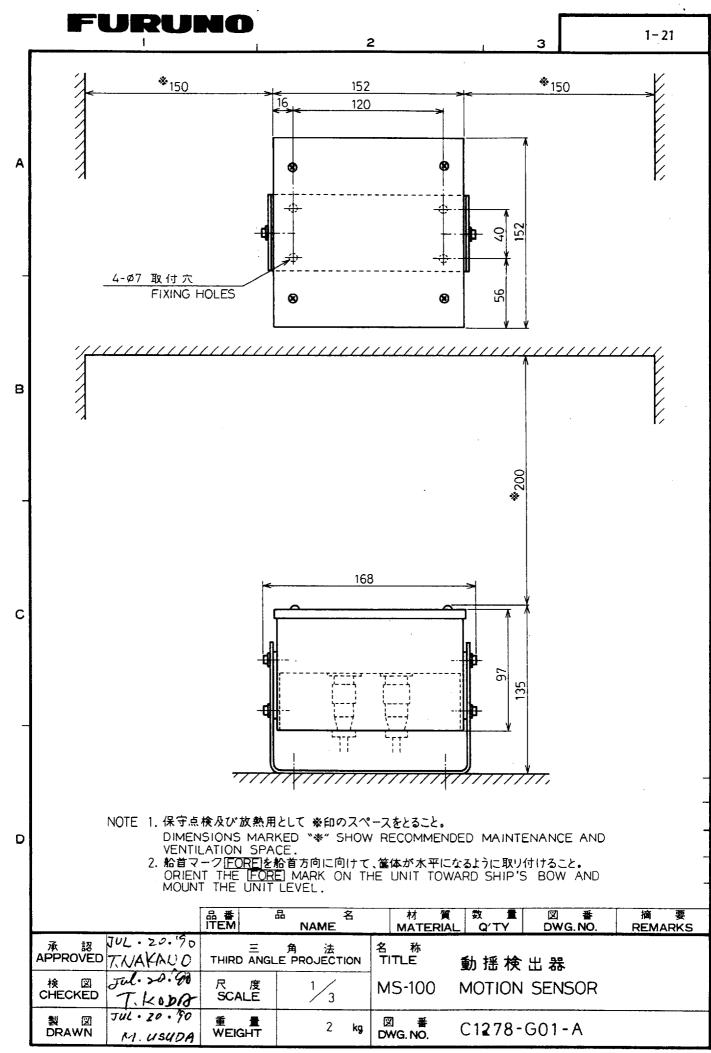


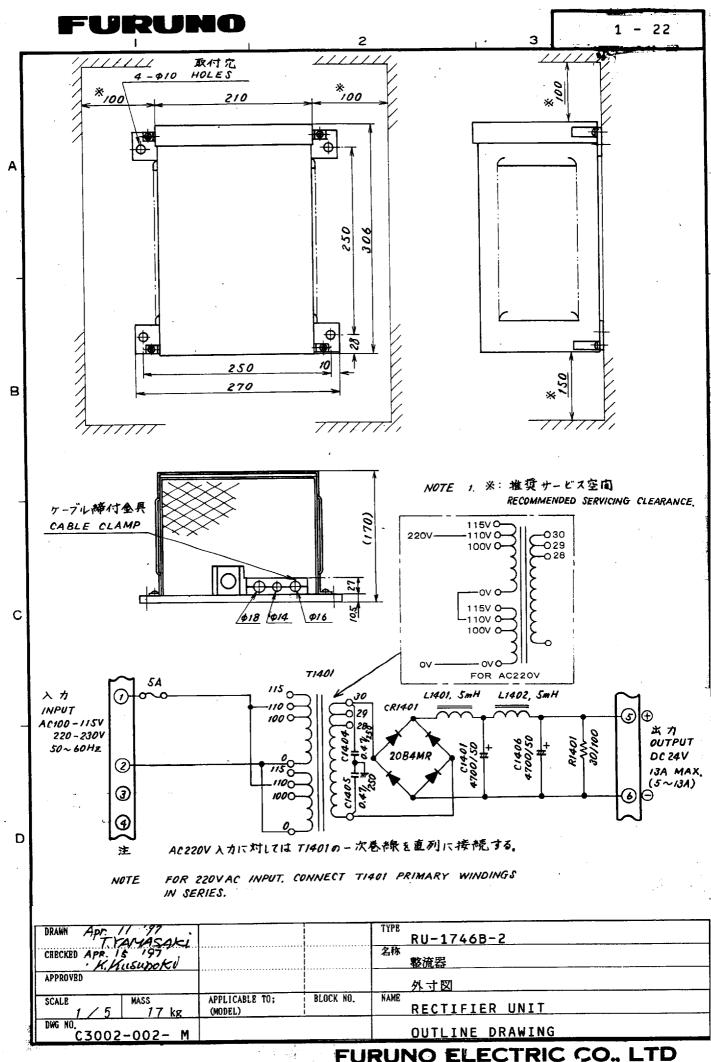
- 1. USE STPG-38-E-C (8"SCHEDULE 80, JIS G3454, CARBON STEEL PIPE FOR PRESSURE SERVICE).
- 2 USE SS41P (JIS G3101, ROLLED STEEL FOR GENERAL STRUCTURE).
- 3. GIVE TWO COATS OF FAST-DRYING RED LEAD PAINT ON OUTSIDE OF TANK. 4. GIVE TWO COATS OF VINYL PAINT AF OR ANTI-FOULING PAINT ON INSIDE OF TANK.
- DO NOT PAINT ON SURFACE OF FLANGE.

D

単位 UNIT:mm		品 養 ITEM			AL Q'TY	図 書 DWG.NO.	摘 要 REMARKS
承 認 APPROVED	NOV. 9 . 177	_	角 法 _E PROJECTION	名 称 TITLE		納タンク外観	
検図 CHECKED	NOV. 8 . 777	尺 度 SCALE	1/5		_	RETRACTION OUTLINE DRA	
製 図 DRAWN	77. 6.28 1). Med	重 量 WEIGHT	1000mm: 73 1800mm: 123 kg 3500mm: 231	図 書 DWG.NO.	/ C1	229-006-	Ģ

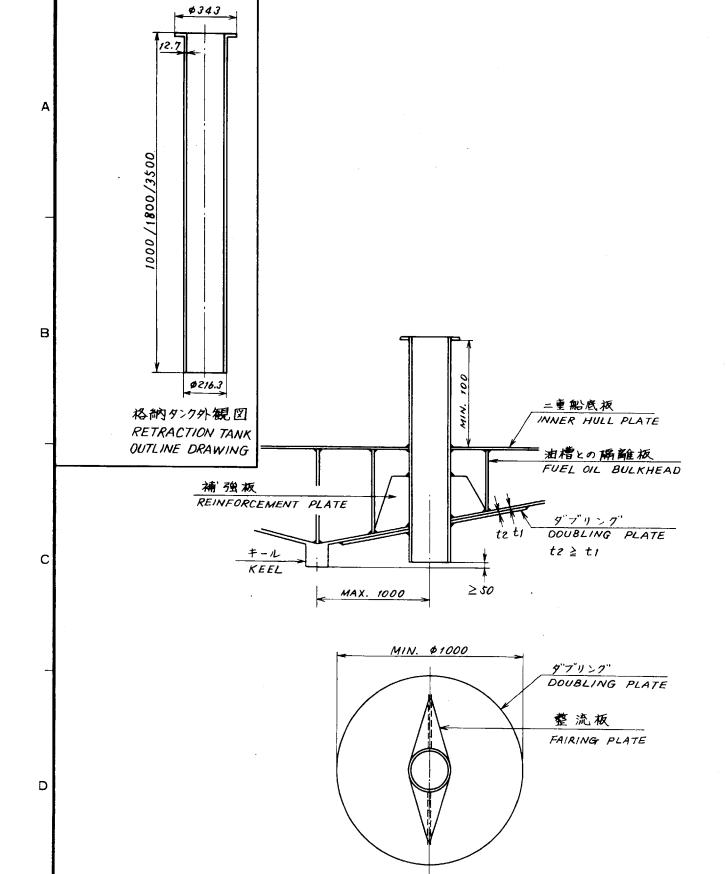






**FURUNO ELECTRIC CO., LTD** 

单位 UNIT: mm



- 1. 格納タンクの機構は次の条件を満すこと。
  - 1) 取付位置は船首からり3(小型船の場合はり2)程度。
  - 2) キールより1加以内。

4

CSH-5

CSH-5 MARK-2

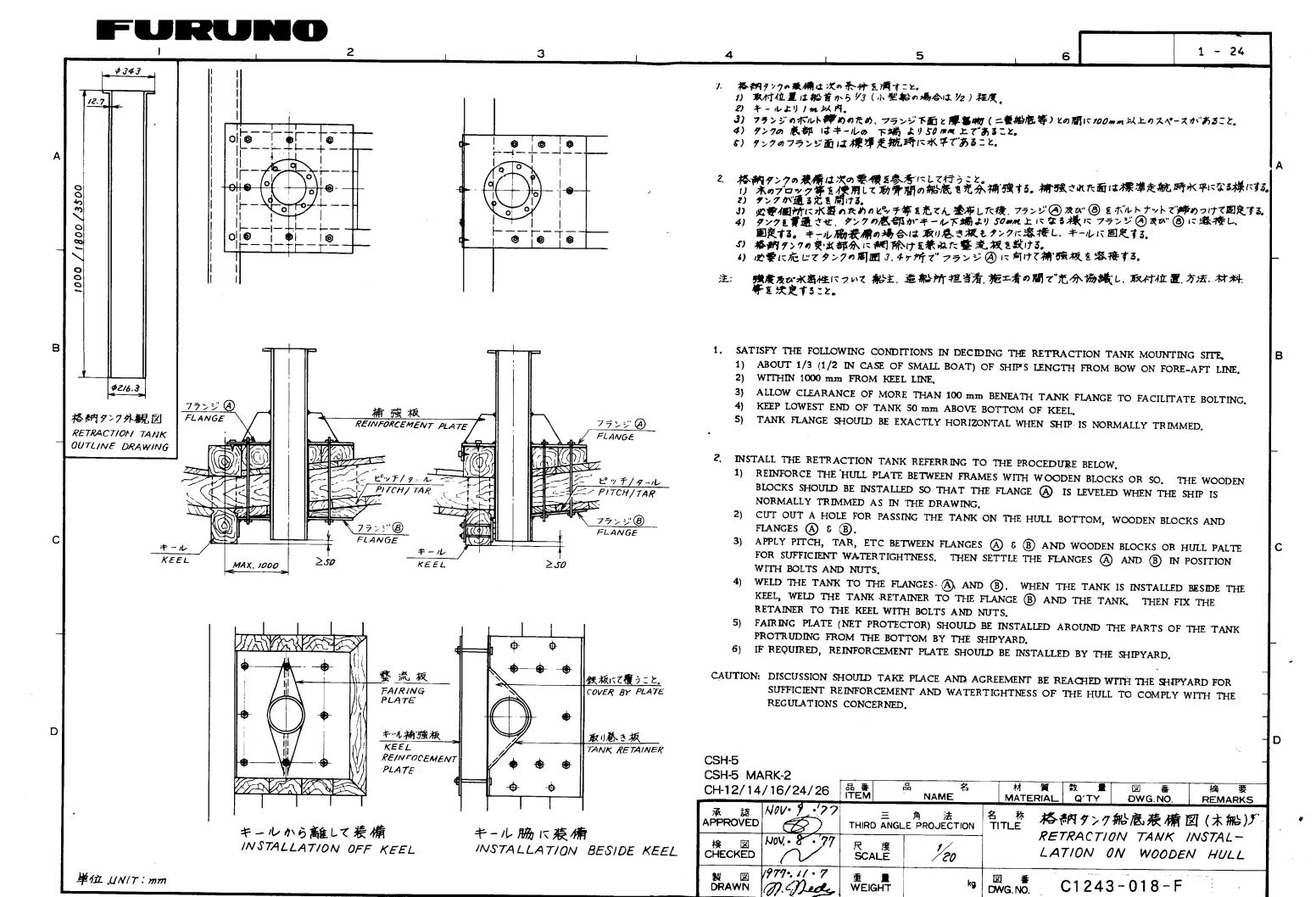
CH-12/14/16/24/26

- 3) フランジのボルト締めのためフランジ下面と障害物 (二重船底等)との間に 100mn以上のスペースがあること。
- 4) タンクの先端はギールの先端より50mm上であること。
- 5) タンクのフランジ面は標準走航時に水平であること。
- 2. 格納タンクの周辺の船底板に径1000程度のダブリングを施すこと。
- 3. 格納タンクの突出部分に調除ける兼ねた整流板を設けること。
- 4 必要に応じて格納タンク周辺に油槽との隔離板をめぐらせること。 またタンク周囲、3.4ヶ所で船底板に向けて補強板を溶接すること。
- 注: 強度反び 水密性について、船主、造船所担当者、施工者の間で完分協議し、取付位置、方法、材料等を決定すること。
- 1. SATISFY THE FOLLOWING CONDITIONS IN DECIDING THE RETRACTION TANK MOUNTING SITE.
  - 1) ABOUT 1/3 (1/2 IN CASE OF SMALL BOAT) OF SHIP'S LENGTH FROM BOW ON FORE-AFT LINE.
  - 2) WITHIN 1000 mm FROM KEEL LINE.
  - 3) ALLOW CLEARANCE OF MORE THAN 100 mm BENEATH TANK FLANGE TO FACILITATE BOLTING.
  - 4) KEEP LOWEST END OF TANK 50 mm ABOVE BOTTOM OF KEEL.
  - 5) TANK FLANGE SHOULD BE EXACTLY HORIZONTAL WHEN SHIP IS NORMALLY TRIMMED.
- 2. DOUBLING PLATE OF ABOUT 1000 mm IN DIA. SHOULD BE INSTALLED BY THE SHIPYARD.

  3. FAIRING PLATE (NET PROTECTOR) SHOULD BE INSTALLED AROUND THE PARTS OF THE
- 3. FAIRING PLATE (NET PROTECTOR) SHOULD BE INSTALLED AROUND THE PARTS OF THE TANK PROTRUDING FROM THE HULL BOTTOM BY THE SHIPYARD.
- 4. IF REQUIRED, FUEL OIL BULKHEAD AND REINFORCEMENT PLATE SHOULD BE INSTALLED BY THE SHIPYARD.

CAUTION: DISCUSSION SHOULD TAKE PLACE AND AGREEMENT, BE REACHED WITH THE SHIPYARD FOR SUFFICIENT REINFORCEMENT AND WATERTIGHTNESS OF THE HULL TO COMPLY WITH THE REGULATIONS CONCERNED.

	品番 品 ITEM	名 NAME	材 質 MATERIAL	数 量 Q/TY	図 番 DWG. NO.	摘 要 REMARKS
承認 NoV· 9-177	≡ f THIRD ANGLE	角 法 名 PROJECTION T	TITLE 76		船底装桶区	• • •
検 図 NOV. 8 · '77	尺 度 SCALE	1/20	RET. LATA		N TANK IN V STEEL I	
DRAWN Mea.	重量 WEIGHT	ka -	図 番 CWG.NO. C	C1243	-017-F	



振れ止め RETAINER

\$345

\$216.3

KEEL

鉄製格納タンク外観図

STEEL RETRACTION TANK

OUTLINE DRAWING

単位 UNIT: mm

12.7

キールより1m以内。

3

71-4

補強板

REINFORCEMENT PLATE

フランジ@

FLANGE

フランジ圏 FLANGE

FRAME

フランジのボルト締めのため フランジ下面と障害物 (二重船底等)との間に 100円の以上のスペースがあること。

- タンクの先端はキールの先端より50mm 上であること。 タンクのフランジ面は標準走航時に水平であること。
- 格例タンクの幾備は、次の要領を参考にして行うこと。
  - フレーム間の船底にタンクが通る兄をあける。
  - タンクあるいは タンクと同径の中子を貫通させ、その回りに フランジA の乗せられる取付台を作り FRPでプレーム、船底間に固定する。
  - フランジ (の) 取付兄に合わせて取付台にボルトを立てておく。 必要があれば フランジ (8) を作りボルトを船底から貫通させる。
  - FRP硬化後タンクあるいは中子を抜き取る。
  - フランジのまタンクに客棒する。
  - A 下面及びタンク外周にFRP-鉄接着剤を塗布した後タンクを取りつける。

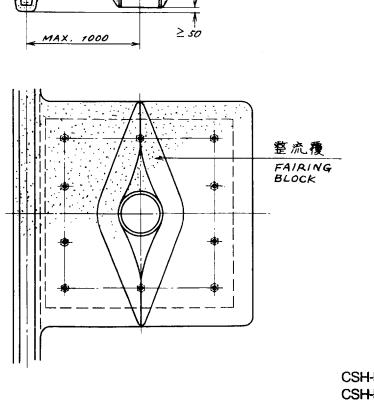
5

6

- 漫水も防ぐため充分にFRPで必要個所を塗り固める。特にタンク回りは流線型に成型し 术による抵抗及U" 気泡発生を最少限におさえる様努めること。
- a) 必要に応じてタンクのフランジ面下部 100mmの位置より隔壁 等に向けて振り止めを設けること。 またフランジ (A) 溶接時、タンクの周囲 3,4ヶ折で フランジ (A) に向けて 補 強板を溶接する。
- 注:強度及び水密性について、船主、造船所担当着、施工者の間で充分協議し、取付位置、方法、 材料等を決定すること。
- 1. SATISFY THE FOLLOWING CONDITIONS IN DECIDING THE RETRACTION TANK MOUNTING SITE.
  - 1) ABOUT 1/3 (1/2 IN CASE OF SMALL BOAT) OF SHIP'S LENGTH FROM BOW.
  - 2) WITHIN 1000 mm FROM KEEL LINE.
  - 3) ALLOW CLEARANCE OF MORE THAN 100 mm BENEATH TANK FLANGE TO FACILITATE BOLTING.
  - 4) KEEP LOWEST END OF TANK 50 mm ABOVE BOTTOM OF KEEL.
- 5) TANK FLANGE SHOULD BE EXACTLY HORIZONTAL WHEN SHIP IS NORMALLY TRIMMED.
- 2. INSTALL THE RETRACTION TANK REFERRING TO THE PROCEDURE BELOW.
- 1) CUT OUT A HOLE FOR PASSING THE TANK ON THE HULL PLATE.
- 2) PASS THE TANK OR A CORE HAVING THE SAME DIAMETER AS THE TANK THRU THE HULL PLATE. MAKE A MOUNTING BED WITH WOODEN BLOCK AND FRP AROUND THE TANK OR THE CORE. THIS BED IS USED TO MOUNT THE FLANGE (A)
- 3) WHEN FABRICATING THE MOUNTING BED, STAND THE BOLTS ON THE BED FOR FIXING THE FLANGE (A). IF NECESSARY, MAKE THE FLANGE (B) TO ENSURE FIXING OF THE FLANGE (A).
- 4) AFTER FRP IS STIFFENED, DRAW OUT THE TANK OR THE CORE FROM THE MOUNTING BED.
- 5) WELD THE FLANGE (A) TO THE TANK.
- 6) APPLY A STEEL-FR? ADHESIVE TO THE TANK AND THE FLANGE (A), AND INSTALL THE TANK WITH FLANGE (A) IN PLACE, SETTLE THE FLANGE (A) WITH BOLTS AND NUTS.
- 7) APPLY FRP AROUND THE PARTS OF THE TANK PROTRUDING FROM THE HULL BOTTOM FOR SUFFICIENT REINFORCEMENT. MAKE A FAIRING BLOCK WITH FRP AROUND THE PROTRUDING PARTS OF THE TANK TO MINIMIZE THE EFFECT OF AERATION
- 8) IF REQUIRED, INSTALL A REINFORCEMENT PLATE WHEN THE FLANGE (A) IS WELDED TO THE TANK. IT IS ADVISABLE TO PROVIDE REINFORCEMENT ANGLES BETWEEN THE TANK AND THE ADJACENT BULKHEAD OR CEILING.

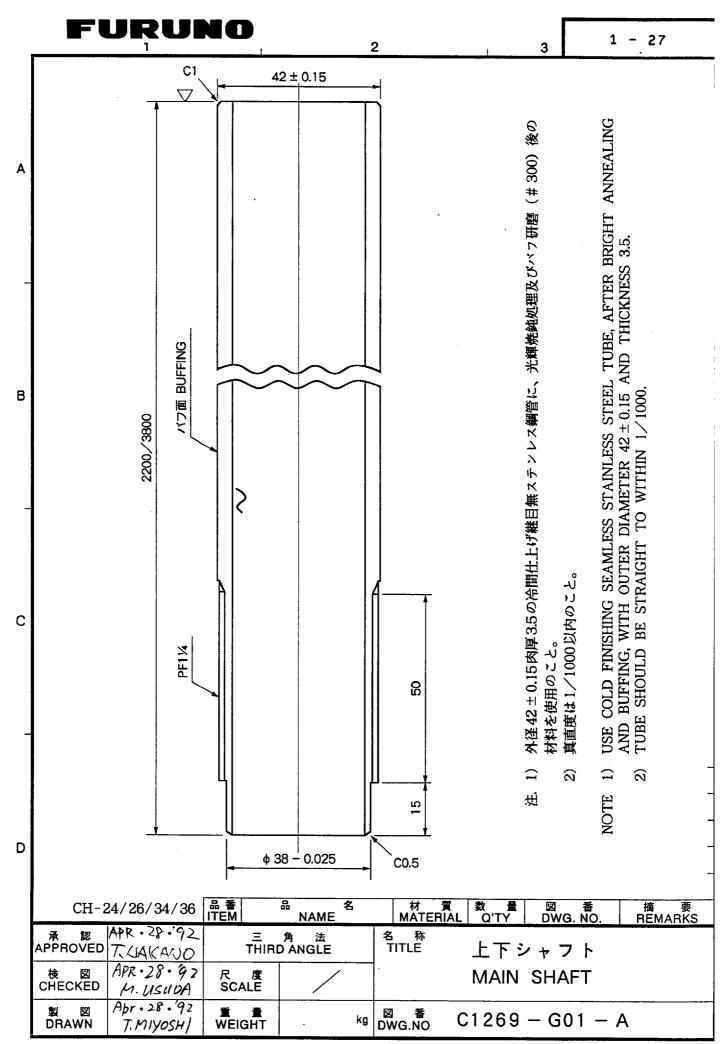
CAUTION: DISCUSSION SHOULD TAKE PLACE AND AGREEMENT BE REACHED WITH THE SHIPYARD FOR SUFFICIENT REINFORCEMENT AND WATERTIGHTNESS OF THE HULL TO COMPLY WITH THE REGULATIONS CONCERNED.

> 質 品 番 数 NAME MATERIAL Q'TY DWG. NO. NOV. 9.177 初 鉄製格納タンク船底装備図(FRP船) APPROVED (\$ THIRD ANGLE PROJECTION TITLE STEEL RETRACTION TANK NOV. 8 .'17  $\mathbb{Z}$ 尺 度 SCALE INSTALLATION ON FRP HULL 1/20 CHECKED 1977-11-7 図 書 DWG.NO. 図 WEIGHT C1243-019-F DRAWN



CSH-5 CSH-5 MARK-2 CH-12/14/16/24/26 1 - 25

		品 番 ITEM	品 名 NAME	M.A	す 質 ATERIAL	数 量 Q´TY	図 番 DWG.NO.	摘 要 REMARKS
承 認 APPROVED	•	= THIRD ANGL	角 法 LE PROJECTION	名 TITLE		•	タンク船底装	
検 図 CHECKED	May. 14.1930	尺 度 SCALE	1/20				ACTION TA	
製 図 DRAWN	July . 18 . 1978	重量 WFIGHT	kg	⊠ DWG I	番 VO ·	C122	0 - 038 - F	



FURUNO ELECTRIC CO., LTD.

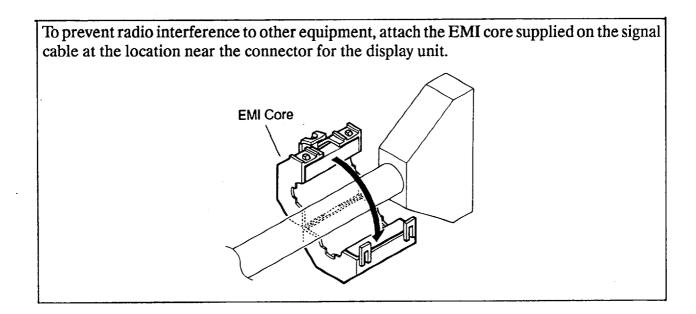
## **CHAPTER 2. WIRING**

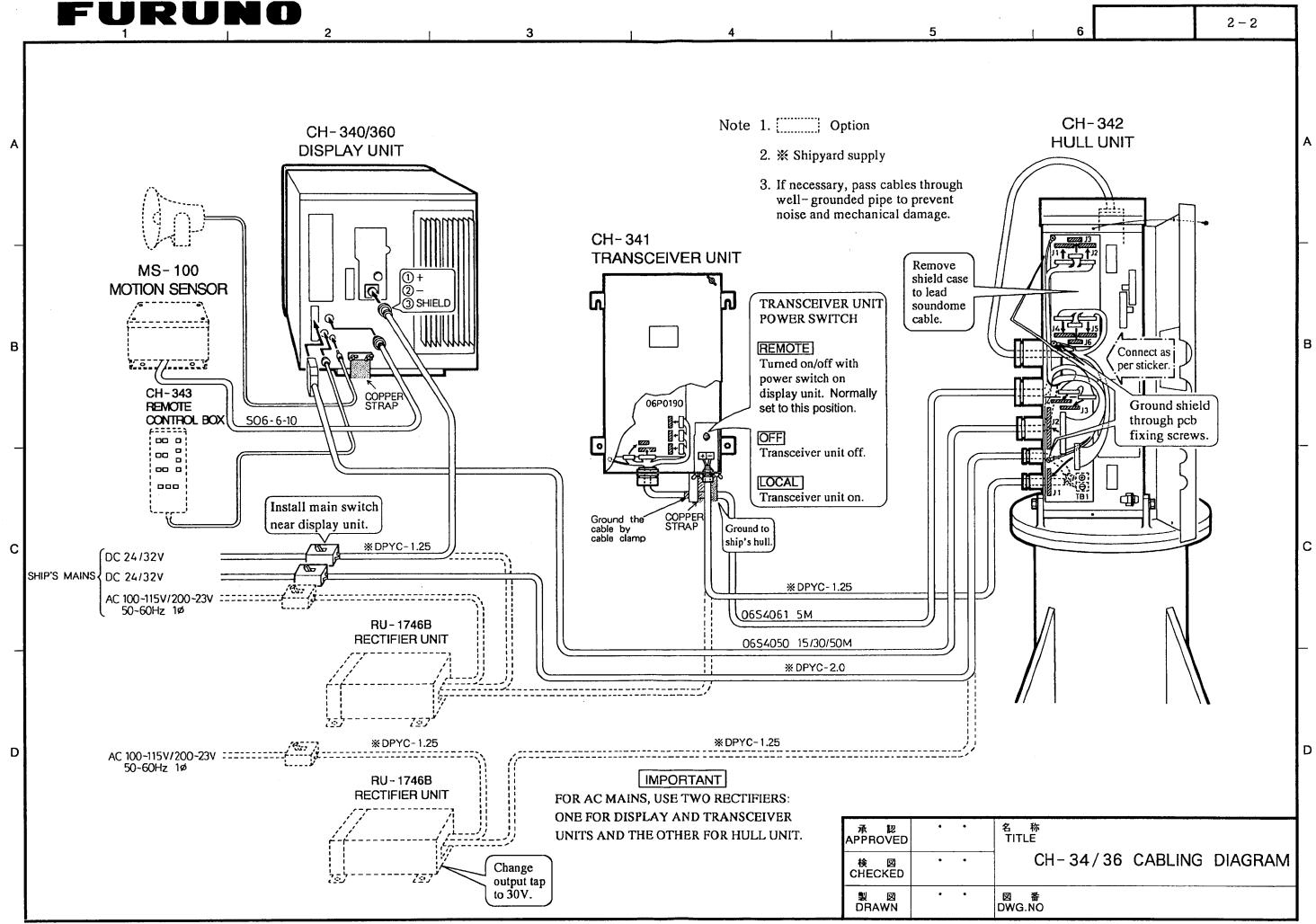
#### 2.1 Wiring between Units

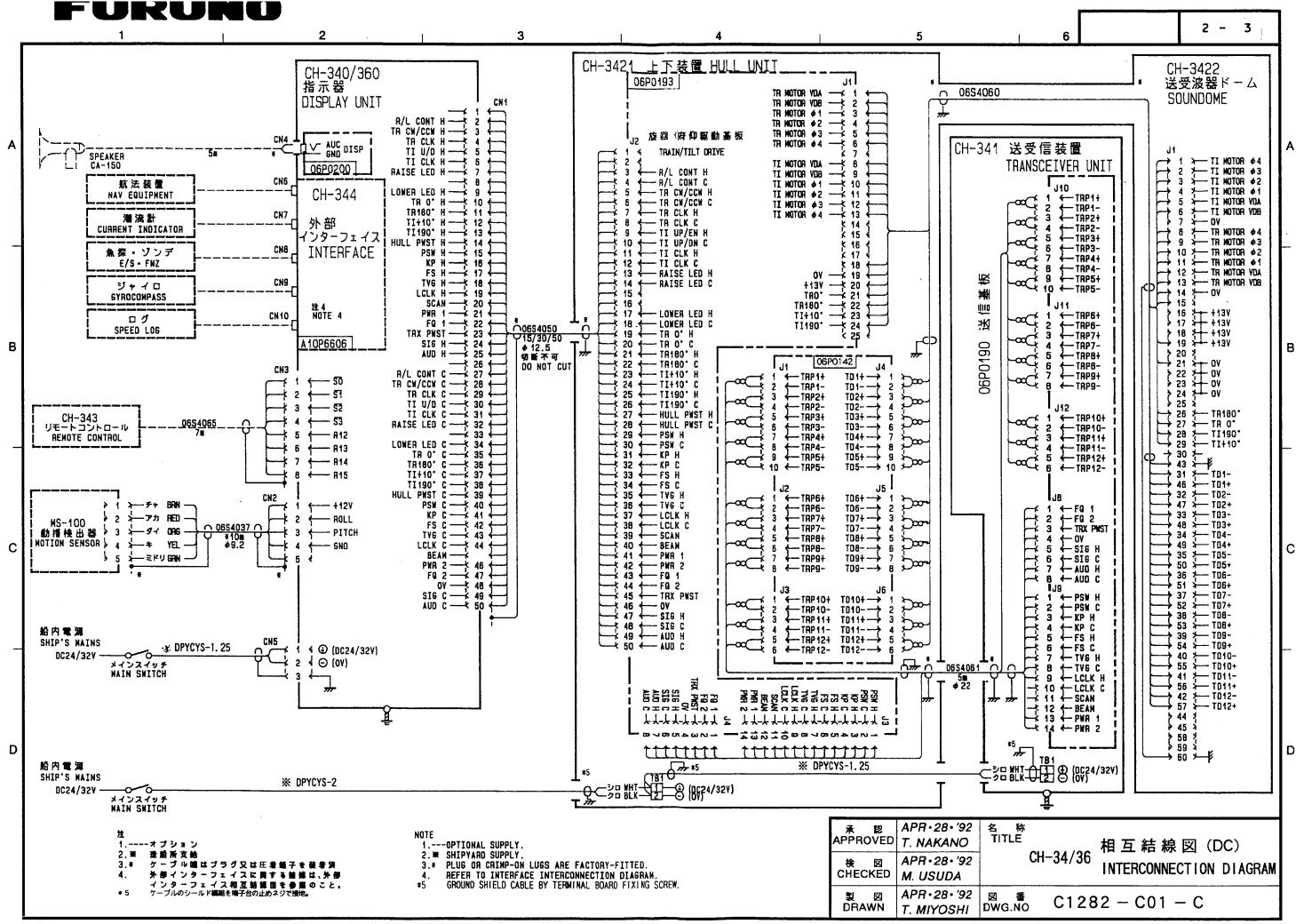
1) The signal cables are fitted with connectors at the factory. Plug them into receptacles on the display transceiver and hull units referring to the interconnection diagrams on page 2-2 to 2-4.

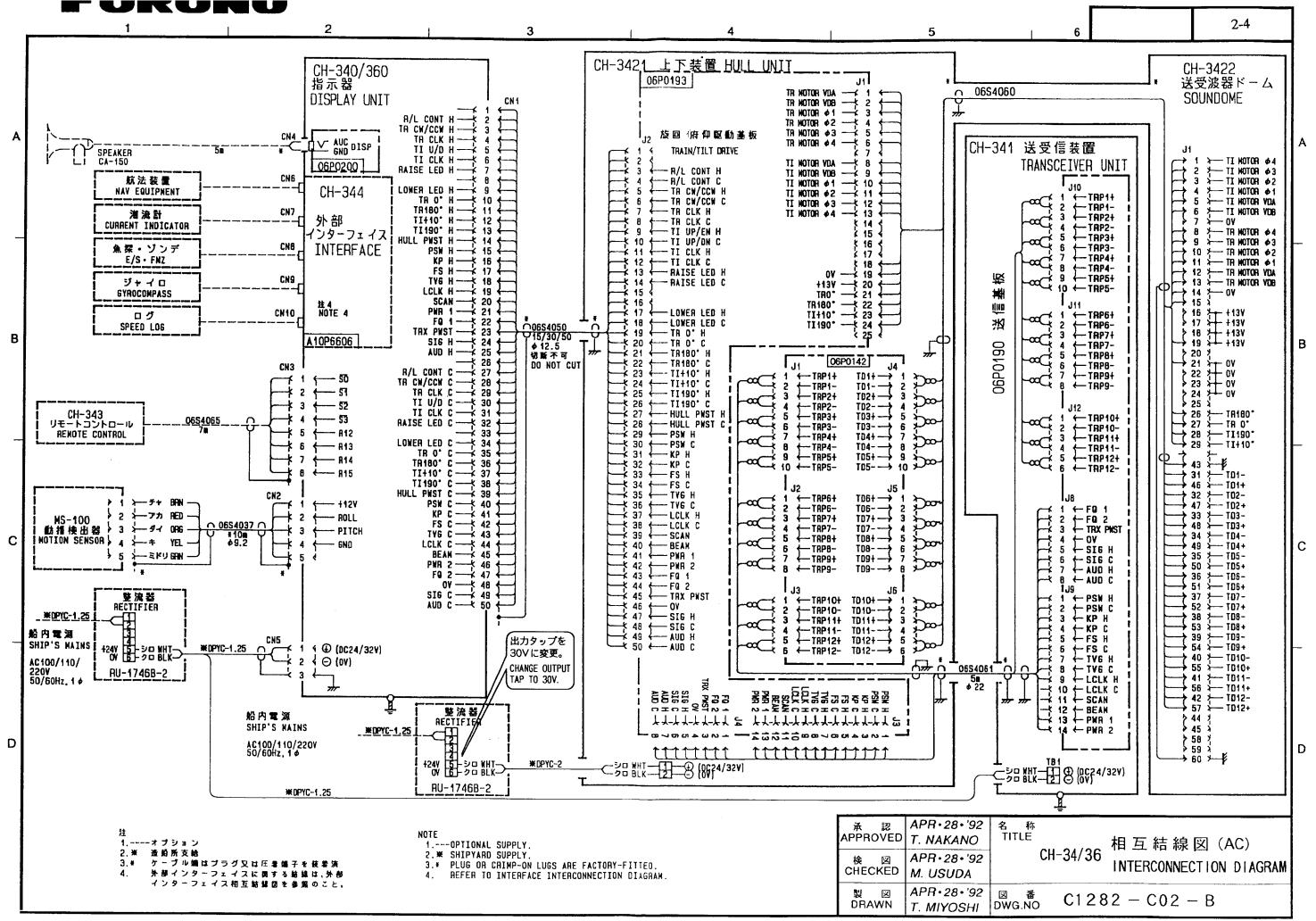
The power cables should be arranged locally and the connector should be fitted.

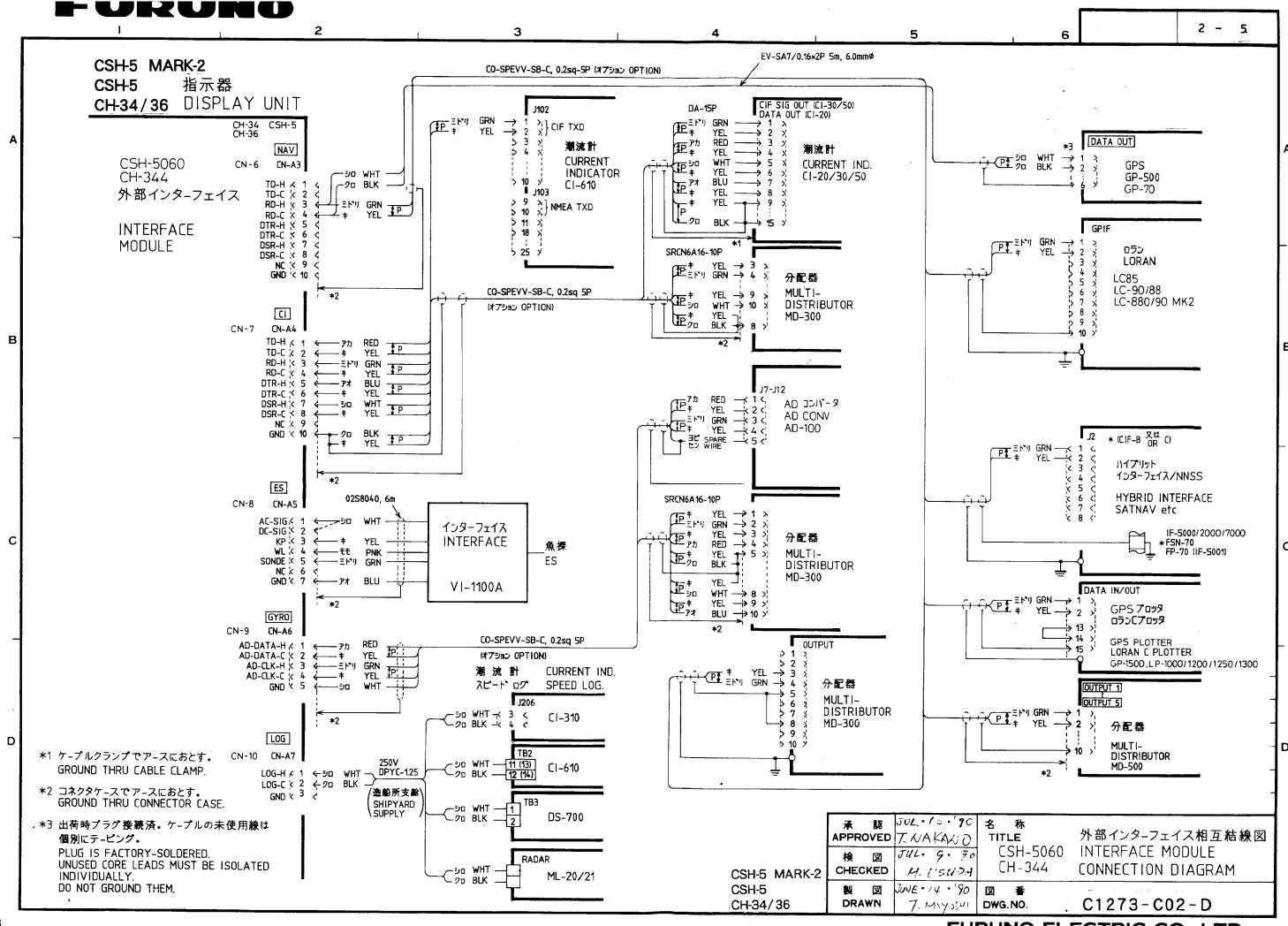
- 2) Install the main switch for the hull unit at an easy to access location. Turning off this switch when the sonar is unused not only economizes the power consumption but also prevents the transducer from slipping down due to vibration, etc.: the electro-magnetic brake of the raise/lower motor is activated when the main voltage is shut down.
- 3) For Ac mains, use two rectifiers RU-1746B: one for the display and transceiver units and the other for the hull unit.









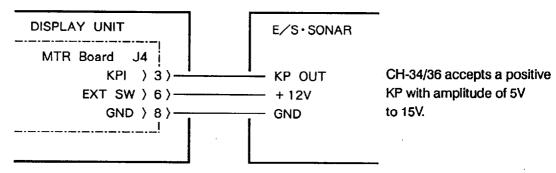


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## 2.2 Synchronizing Transmission with Echo Sounder or Other Sonar

To synchronize the transmission of the CH-34/36 with an echo sounder and other type of sonar, make connections as shown below.

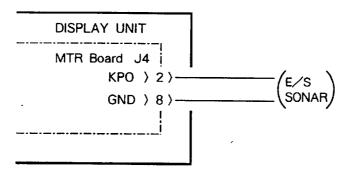
#### 1) Connection



#### 2) Menu Setting

Set the TX EXT SYNC item of the menu to ON. Refer to the operator's manual for operation on the menu.

Note: To output KP of the CH-34/36 to other sonar or echo sounder, make connections as shown below.



# CHAPTER 3. AFTER-INSTALLATION CHECK AND ADJUSTMENT

## 3.1 General Check

## 3.1.1 Check on Slipway or in Dry-dock

No.	Check Item	Ratings	Refer to
1	Retraction Tank Level	On-keel Installation  Flush with Keel  Off-keel Installation  Within 1m Above Keel	1-1 1-18
2	Clearance between transducer and bottom of retraction tank when transducer is completely retracted by hand crank.	1 cm	1-8 1-18 ·
3	Transducer Travel (lowered by hand crank) Note: When checking, a clearance of approximately 1m is required under the bottom of the transducer.	Aprrox. 36cm	
4	Manual Raise/Lower of Transducer	Transducer can be raised/lowered smoothly with hand crank	1-11
5	Transducer Heading	Bow mark inscribed on main shaft should face ship's bow.	1-8

## Before the ship is launched, check the following points

No.	Check Item	Ratings	Refer to page
	Wiring Check	1) All cables are correctly connected.	
		2) All lead wires are tightly fixed with contact pins or crimp-on lugs.	
		3) All screws are securely tightened.	
1		4) Cables are firmly bound.	
		5) Cable shields are properly grounded.	
2	Rejecting Source of Noise and Interference	1) Noise generating machines are not placed nearby, e.g., motor, radiotelephone, transmitter unit, TV set, etc.	
		2) Magnetic devices are not placed in the vicinity of display unit.	
3	Grounding	Each unit is grounded with a copper strap.	1-13
4	Ship's Mains Voltage	Ship's mains voltage is stable at 24/32VDC.	
5	Watertightness	Water should not leak from the main body flange or along the main shaft.	
6	Heading Alignment	A target is displayed in the correct bearing.	3-4

### 3.2 Adjustment of Transceiver Unit

#### 3.2.1 Selecting Audio Frequency

Select audio frequency 1000Hz or 900Hz by jumper connector JP2 on 06P0192 board. The factory setting is 1000Hz. Refer to Fig.3-1.

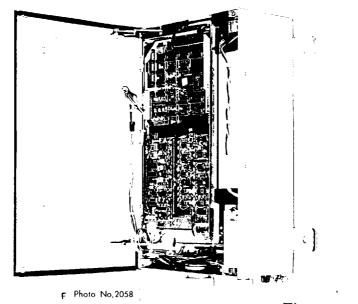
HI ---- 1000Hz LO ---- 900Hz

#### 3.2.2 Signal Offset Adjustment

When noise appears on the screen, adjust R61 (offset) on 06P0192 board. Turning R61 clockwise slices off low level signals in similar way to the CLUTTER control on the display unit. (While the CLUTTER control on the display unit eliminates low level signals without changing signal level of strong signals, R61 shifts signal level of all signals.) When the offset adjustment is unnecessary, set R61 fully counterclockwise. Refer to Fig.3-1 for location of R61.

#### 3.2.3 Adjustment of Horizontal Beamwidth

When the user wishes echoes to be displayed with a high resolution, turn R40 on 06P0192 board clockwise for sharper horizontal beamwidth. Do not turn it excessively clockwise, or an echo which should be displayed as single solid mass may become unsolid or split into small few masses. Normally it is set at the mid-point of its travel.



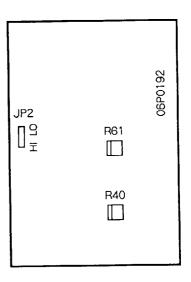
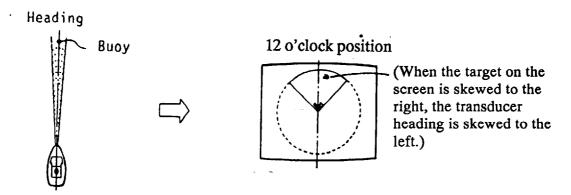


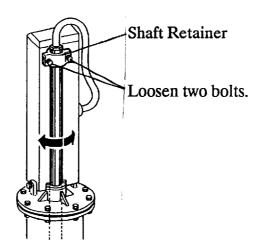
Fig.3-1

## 3.2 Heading Alignment

1. To correct the ship's heading, locate a target in the bow direction (a buoy, etc.) and display it on the screen at a close range. The heading alignment is correct when the target is displayed at 12 o'clock direction on the screen.



2. When the heading alignment is incorrect, rotate the main shaft after loosening four bolts on the shaft retainer.

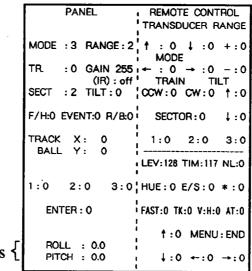


3. After the adjustment, retighten the bolts.

### 3.3 Motion Sensor (Option) Adjustment

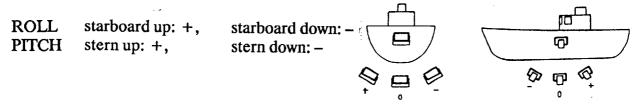
As started in paragraph 1-5, when the ship has a semi-permanent inclination (stationary inclination of ship), offset it as follows. Inclination of up to 10° approximately can be corrected.

- 1. Turn on the power while pressing the EVENT key and keep the EVENT key pressed until beep sounds. The selfcheck menu will be displayed.
- 2. Select KEY test item and press the MENU key to display the key test screen.



ROLL/PITCH angles {

- 3. Read ROLL/PITCH angles on the screen.
- 4. By using the clinometer on the ship or by other means, measure ship's semi-permanent inclination angle. Take the polarity of the angle as follows:

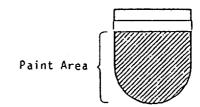


5. Adjust the ROLL/PITCH potentiometers R9 and R12 on the MTR board 06P0201 in the display unit so angle readout on the screen agrees with the angles measured at step 4

## 3.4 Soundome Painting

When the soundome is painted to prevent oysters and shells to grow on its surface, observe the following precautions.

- 1. Use anti-fouling paint type MARINE STAR 20 manufactured in Japan by Chugoku Marine Co., Ltd. Other type should not be used.
- 2. Paint only the plastic portion of the dome. Painting the metal portion causes electrolytic corrosion.



## 3.5 LED Status Check

Check the LED status on the pc boards.

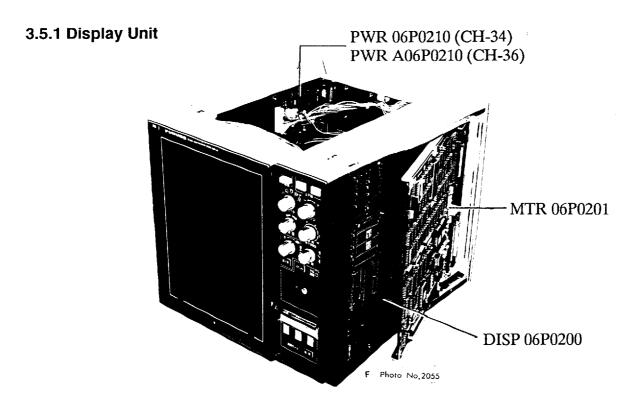
## Display unit setting

Range: Tilt: 0°

Mode: 400m

TX Output Power: C (Max.)

TX Rate: 10



Off:

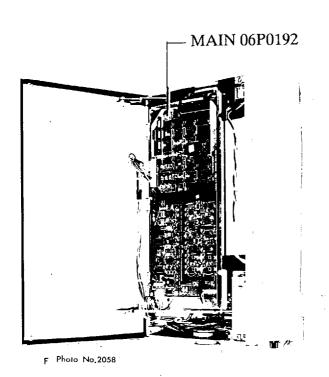
Flicker:

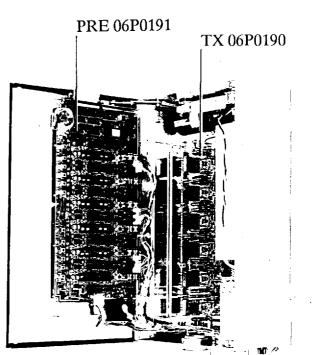
Light:

PCB		LED		Remarks
	No.	Signal	Status	
DISP	CR1	R/L CONT	•	Off except when the transducer is being lowered.
06P0200	CR2	HALT	•	Lights when CPU stops.
	CR3	BERR	•	Bus error
	CR4	+ 12V AUDIO	0	+ 12V power supply for audio amp
	CR27	KP	•	Flickers during transmission
	CR32	+5V	0	
	CR33	+12V	0	
	CR34	-12V	0	
	CR10	+ 12V	0	
	CR11	+5V	0	
	CR12	TIM	•	

	CR13	TI CLK		Lights while TILT lever is pressed and goes off while released.
	CR14	TR CLK	•	Flickers while transducer training is in operation and goes off while transducer is stopped.
	CR15	L CONT	•	Off except when the transducer is being lowered.
	CR25	Tl 190°	•	Lights momentarily when transducer tilt angle is 90° or 190°.
	CR26	TI +10°	•	Lights momentarily when transducer tilt angle is + 10° or 90°.
	CR27	TR 180°	•	Lights momentarily when transducer is trained to 180° direction.
	CR28	TR 0°	•	Lights momentarily when transducer is trained to 0° direction.
	CR32	HULL	0	Lights while ship's mains is supplied to hull unit.
	CR33	KP	•	Flickers during transmission
	CR35	EXT	•	Lights whenever KP for synchronous transmission is fed from external equipment. (Connection to external equipment is necessary.)
	CR36	D0	•	Flickers by received echoes.
:	CR37	D1	•	
	CR38	D2	•	
	CR39	. D3	•	
PWR Board 06P0210	CR8	T∨	0	Power supply for color monitor (CH-34: +90V, CH-36: +110V)
(CH-34) A06P0210	CR11	+12V	0	
(CH-36)	CR12	-12V	0	
	CR13	+5V	0	
	CR26	F12V	0	
	CR38	IN 5V	•	Lights momentarily when overvoltage protector for 5V operates.
	CR39	IN 12V	•	Lights momentarily when overvoltage protector for 12V line operates.

## 3.5.2 Transceiver Unit





F Photo No. 2057

Off:: ●

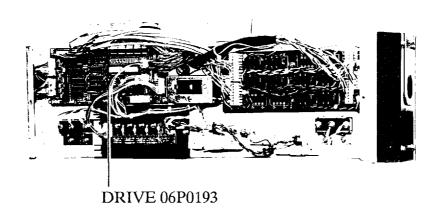
Flicker: ①

 $\textbf{Light:} \bigcirc$ 

РСВ		LED		Remarks
	No.	Signal	Status	
TX Board	CR11	+5V	0	
06P0190	CR12	+ 12V		
	CR13	+130V	0	
	CR39	TX1	•	Flickers during transmission
	CR40	TX12	•	Ditto
	CR41	TX11	•	Ditto
	CR42	TX2	•	Ditto
	CR43	TX3	•	Ditto
	CR44	TX10	•	Ditto
	CR45	TX9	•	Ditto
	CR46	TX4	•	Ditto
	CR47	TX5		Ditto
	CR48	TX8	•	Ditto
	CR49	TX7		Ditto
	CR50	TX6		Ditto
PRE Board	CR1	+5V		
06P0191	CR2	+ 12V	0	
	CR3	-12V	0	

MAIN Board	CR1	+5V	0	
06P0192	CR2	-12V	0	
	CR3	+ 12V	0	
	CR4	AUD	•	Flickers by audio signal.
	CR16	FS	0	FS signal
	CR17	TVG	•	Digital TVG signal
Ì	CR18	LCLK	0	TVG signal latch clock
PWR Board	CR9	-12V	0	
06P0172	CR10	+ 12V	0	
	CR11	+5V	0	
	CR12	+130V	0	

## 3.5.3 Hull Unit



Off: ●	Flicker: ①	Light: $\bigcirc$
Oil.	THURCH.	Ligit.

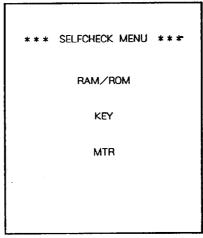
РСВ	LED			Remarks
	No.	Signal	Status	
DRIVE Board	CR12	TR0°	•	Lights momentarily when transducer is trained in 0° direction.
06P0193	CR13	TR180°	•	Lights momentarily when transducer is trained in 180 direction.
	CR14	TI + 10°	•	Lights when transducer is tilted to +10° or 90°.
	CR15	TI90°	•	Lights when transducer is tilted to 90°.
	CR16	+ 13V	0	
	CR18	TR CLK	0	Lights while transducer training is in operation.
	CR19	TI CLK	•	Lights while TILT lever is pressed and goes off when released.
	CR20	+ 13V	0	

#### 3.6 Selfcheck

The CH-34/36 has four built-in diagnostic selfchecks which check it for proper operation. Execute the checks after all the installation jobs are completed.

#### 3.6.1 Turning on/off Selfcheck

1. Turn on the CH-34/36 while pressing the EVENT key and keep press the EVENT key until a beep is heard, and the selfcheck menu as shown below is displayed.

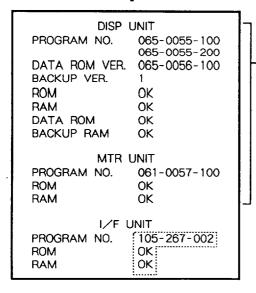


- 2. Select an appropriate selfcheck by operating 1 keys on sub-panel 2.
- 3. Press the MENU key to execute the selected selfcheck.
- 4. To return to the selfcheck menu, press the MENU key again.
- 5. To exit from the selfcheck screen, turn off and then on the CH-34/36.

#### 3.6.2 Description of Selfchecks

#### RAM/ROM Check

This checks the major circuits in the display unit for proper operation.



Program numbers of DISP, MTR and I/F boards are displayed, and RAM/ROM are checked for proper operation.

If the interface board (option) is not incorporated, the check results enclosed by dotted lines are not displayed.

#### **KEY Check**

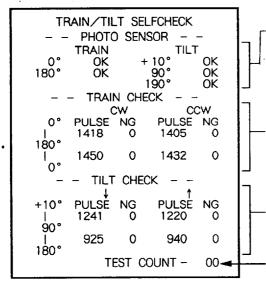
This checks the operating switches on the main panel for proper operation.

PANEL	REMOTE CONTROL TRANSDUCER RANGE
MODE : 3 RANGE: 2	↑ : 0 ↓ :0 +:0 MODE
1	← : 0 → :0 - :0
SECT : 2 TILT: 0	CCW:0 CW:0 1:0
F/H:0 EVENT:0 R/B:0	SECTOR:0 1:0
TRACK X: 0	1:0 2:0 3:0
BALL Y: 0	LEV:128 TIM:117 NL:0
1:0 2:0 3:0	HUE:0 E/\$:0 *:0
ENTER: 0	FAST:0 TK:0 V:H:0 AT:0
DOLL E	1:0 MENU:END
ROLL : 5 PITCH : 4	1:0 ←:0 →:0

If the value changes when each switch is operated, the switch is normal.

#### **MTR Check**

This checks the transducer training and tilting functions for proper operation.



This checks the photo sensors which detect the reference angles for training/tilting operations.

This checks the transducer training operation. The four digit figures show the number of pulses used to train the transducer by 180°. If they are abnormal, NG (No Good) count increases by one.

This checks the transducer tilting operation. If the number of pulses used to tilt the transducer is abnormal, NG count increases by one.

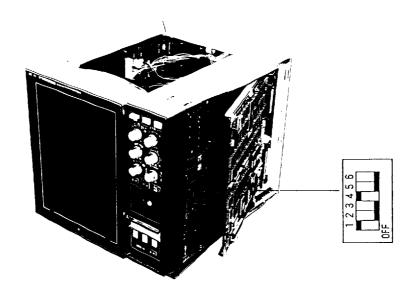
Above checks are repeatedly executed. This count increases by one upon completion of one cycle of checks.

# CHAPTER 4. CHANGING SPECIFICATIONS

According to user requirements, and in order to render use even easier, the operating specifications can be changed to those shown in the following tables.

## 4.1 Changing DIP Switch Setting

The switches used to change the specifications are located on the DISP board in the display unit. Change settings to fit user's particular requirements.



Function	No.	Description				
Input Signal	1	ON Echo Signal	OFF Test Signal			
	2	OFF	ON			
Echo Dynamic Range	3		On: Wide Off: Narrow Choose "wide" for better sensitivity of weak echoes.			
Echo Smoothing	4	On: Smoothing on Echo smoothing streto				

## 4.2System Menu Setting

#### **4.2.1 Operating Procedure**

- 1. Turn on the power while pressing MENU key.
- 2. Select item with ★ keys and set parameter with ★ keys.
- 3. To return to the normal display, turn off/on the unit.

SYSTEM MENU POSITION DISPLAY: OFF L/L LOP DEPTH DISPLAY : OFF ON HEADING DISPLAY : OFF TRUE AZ NORTH MARK : OFF ON TRACK : 10R 20R HEADING DATA : GYRO NAV LOG PULSE : 200 400 NAV DATA : GPS LORAN C LORAN A DR DECCA DATA FORMAT : CIF NMEA OTHERS BAUD RATE : 1200 2400 4800 TVG CORRECTION : OFF 1/2 : **M** FΑ FT HIRO 言語/LANGUAGE : 和文 English BACKUP CLEAR : NO YES

#### 4.2.2 Explanation of System Menu Items

ltem	Parameter	Description	
Position Display	Off	Selection of ship's position display	
,	L/L	L/L Latitude/Longitude	
	LOP	LOP Line Of Position of Ioran system	
Depth Display	OFF	On/off of depth data fed from color video sounder	
<b></b>	ON	•	
Heading Display	OFF	Selection of heading display	
	TRUE	True: True bearing	
	AZ	AZ: 16 azimuth bearing	
North Mark	OFF	On/off of north mark	
	ON		
Track .	10R	Selection of length of ship's courseline plotting	
	20R	10R: Ten times the range in use	
		20R: Twenty times the range in use	

HDG/SPD Data	GYRO.LOG CI NAV	Selection of data used for ship's courseline plotting Gyro.Log: Data from gyrocompass and speed log Cl: Data from current indicator NAV: Data from navigation equipment	
Log Pulse	200 400	Setting pulses-per-mile (pps) specifications of speed log 200 200pps 400 400pps	
Nav Data	GPS LORAN C LORAN A DR DECCA OTHERS	Selection of source of ship's position data  NOTE: For sat-nav combined with Loran-A or C in FURUNO CIF data format, select Loran-A or Loran-C.	
Data Format	CIF NMEA	Selection of input data format	
Nav Baud Rate	1200 2400 4800	Selection of baud rate of the data input from the navigation equipment	
CI Baud Rate	1200 2400 4800	Selection of baud rate of the data from the current indicator	
V-Mode Manu Train	HALF FULL	Selection of manual training sector width of the vertical fan mode Half: Half circle Full: Full circle	
TVG Correction	Off 1/2	Changing TVG curve to compensate for absorption attenuation of ultrasonic wave in water	
	1	OFF: Absorption attenuation neglected	
		1/2: 1/2 of theoretical absorption attenuation value added to TVG curve	
		Full theoretical absorption attenuation value     added to TVG curve	
Unit	M FT FA HIRO	Unit selection	
Language	ENGLISH	Select English. The other is Japanese.	
Backup Clear	No Yes	Select "Yes" to reset the system menu to the default settings.	

# APPENDIX 1. INSTALLATION OF INTERFACE MODULE CH-344

The interface module CH-344 is required to connect the CH-34/36 navigation equipment, echo sounder, etc. and it is usually installed in the display unit at the factory. When it is separately supplied, install it as follows.

- 1) Remove the display unit cover.
- 2) Remove the blind plate on the rear of the display unit.
- 3) Remove three fixing screws for the MTR board (06P0201).
- 4) Install the interface board and plug in the flat cable to J11 on the DISP board (06P0200).
- 5) Connect the cables of the connector plate assembly to the DISP and interface boards.

CN-6 (Nav)	- <b>J</b> 3
CN-7 (Current Indicator)	-J4
CN-8 (Echo Sounder, Sonde)	-J8 (DISP Board)
CN-9 (Gyrocompass)	J6
CN-10 (Speed Log)	J6

- 6) Plug the XH connector assembly supplied to J5 on interface board and J7 on DISP board.
- 7) Fix the connector assembly on the rear plate.

